

Improving Durability TSCS – Measuring Asphalt Density

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1. INTRODUCTION

1.1. BACKGROUND

The high level objectives of the Agency are value for money, driving innovation and improving efficiency. The Agency has a range of intrusive and non-intrusive pavement investigation techniques that are employed to assess the condition of the network, to evaluate safety critical performance and the pavement's structural capacity.

Thin surface Course Systems (TSCS) are asphalt materials that are safe to drive on, easy to install and help to reduce road traffic noise. They were originally developed in France and Germany and were introduced on UK roads in the late 1990's. Previous research has shown that these materials can last for up to 16 years, even on roads with very high traffic levels. However, recent harsh winters have led to some road surfaces deteriorating prematurely and very rapidly. Like many organic substances, bitumen slowly oxidises when in contact with air. The degree of oxidation (often simply referred to as "ageing") is highly dependent on the temperature, time and the thickness of the bitumen film. It is recognised that over time, asphalt ageing can lead to pothole formation.

There is a view that density, air voids and binder content have a significant role on the in situ performance of road surfacings, and ultimately TSCS service life. A detailed study to investigate the possible testing methods for measuring TSCS in situ air voids and to develop a most suitable method for these systems is therefore considered important.

This project forms part of a wider Highways England strategy to develop value for money surfacing materials and treatments for the strategic road network that are safe and durable, whilst minimising road traffic noise and embodied carbon. Previous research reports have shown that thin surfacings can deliver equivalent whole life cost benefits to traditional surfacings but with the added benefit of reducing traffic noise.

The primary objective of this project is to ensure that asphalt surfacings continue to deliver value for money on the strategic road network and to maximise the benefit from innovation.

On 6 January 2016, AECOM (formerly URS) was commissioned by Highways England to carry out a study on "Improving Durability of TSCS", under the Framework for Transport Related Technical and Engineering Advice and Research –Package Order Ref: 671(4/45/12)ARPS. The project aims to develop a non-destructive test method to assess in situ density of asphalt surfacing. This work has been divided into the following sub-tasks:

1. Complete a literature study on the testing methods available worldwide for measuring TSCS density. To shortlist the most suitable options and complete trials for each option.
2. To develop a practical method for measuring TSCS density in-situ.

This report presents findings from the literature study and discusses the suitability of current non-destructive density testing equipment.

1.2. COMPACTION AND DENSITY OF HOT MIX ASPHALT

Compaction is essential in the construction of hot mix asphalt (HMA) to ensure long-term durability. For base and binder course, the compaction level is monitored and controlled by the in-situ void content specified in Manual of Contract Document for Highway Works, Volume 1, (MCHW 1) Clauses 929, 930 and 937. However currently there is no such requirement specified for TSCS.

Void content that is either too high or too low can lead to premature failure. A pavement with a high void content as a result of poor compaction is prone to water penetration and defects such as cracking and ravelling. On the other hand, a pavement with very low void content may lead to rutting and shoving (Brown 1990). A general threshold value of 7% applies for a newly constructed asphalt concrete dense base and binder course (MCHW 1 Clause 929). However no threshold currently applies to TSCS. The void content is determined in accordance with BS EN 12697-8 using the bulk density and the maximum density according to BS EN 12697 – 6 and 5 respectively.

Due to the nature of the composite mixture material, as Romero (2002) states “no absolute density value can be defined and some variations in density measurements exist”. Two commonly used methods of measuring in situ asphalt bulk density are core and nuclear density gauge (NDG). The former requires extraction of core samples for further laboratory assessments. It is the only direct measurement of the asphalt density but has drawbacks of increased time and cost needed from core extraction to the end of testing is time-consuming and costly. The NDG is a quick and non-destructive alternative solution, but has practical limitations and health and safety risks due to its use of radioactive material. There are also stringent requirements on store, transport and use of the NDG and training and licensing of the operatives. Hence, there was a need to replace NDG with safer and easier-to-operate equipment. Furthermore the effectiveness of NDG to determine in situ density of thin asphalt layers (such as TSCS) is unknown.

Electromagnetic devices for HMA density measurements were made commercially available in the late 1990s. They are non-radioactive, light-weight, safe, easy to use and can provide rapid and reliable readings. Many studies on the electromagnetic devices have been published in the last 15 years in the United States, which recommended these devices were “at least as good as nuclear

density gauges” (Williams et al 2007). Nevertheless, there are conflicting views on the application of these devices including whether they should be used to provide density values (referred to as “Quality Assurance”) or to provide density changes only (referred to as “Quality Control”). Other technologies, which are claimed to be successful alternatives for measuring in-situ asphalt densities, are also introduced in this report. However, many of these are still at the research stage and not commercially available.

1.3. OBJECTIVE AND SCOPE

The primary objective of this research is to review and evaluate the available methods of measuring the density of hot mix asphalt (HMA) pavements, with a specific interest on thin asphalt layers in the range of 30mm to 50mm. Non-destructive methods using NDG, electromagnetic instruments and other techniques, such as ground-penetrating radar, step frequency radar and the newly-developed compacting monitoring system are compared with the conventional coring method. The advantages and limitations of these methods are examined. Furthermore, some national and international cases are studied to collate lessons and compare different technologies. Some technologies are still at the research stage and in need of further development before they can be adopted by the industry. They are briefly introduced in the review to demonstrate possible future developments. However, more emphasis is given to the established technologies which could be more readily applied.

1.4. REPORT OUTLINE

The common methods for measuring asphalt density - core method and NDG method are described in Section 2. Section 3 summarises other non-destructive methods including capacitive electromagnetic devices, the electromagnetic wave-based methods, ultrasound technology and the recent development of compaction monitoring systems. All these density measurement methods are evaluated by their attributes, on basis of which recommendations are given in Section 4. Section 5 discusses the testing completed based on Section 4 recommendations and Section 6 presents results and analysis for testing completed at AECOM Nottingham’s Test Pit Facility.

2. DENSITY MEASUREMENT – COMMON METHODS

2.1. CORE METHOD

Although the core method is costly and time-consuming it is still widely used. Intrusive coring and reinstatement creates a local weakness in the pavement which can fail later on. Nevertheless, the core method is the only direct measurement of the density and still plays an important role for calibrating other methods.

Air void content is determined according to BS EN 12697-8 by comparing the bulk density with the maximum density. BS EN 12697-5 procedure A is specified for testing maximum density. BS EN 12697-6 includes four procedures for testing core bulk densities, depending on the void content and water absorption of the samples. Table 1 is reproduced from BS EN 13108-20 and lists the procedures for bulk densities according to the design void content and asphalt material. UK guidance for interpretation, BS 594987, specifies the BS EN 12697-6 Procedure A for performance-related HRA surface course and Procedure B for designed dense base and binder AC mixtures and SMA binder course.

Table 1: Summary of void content testing based on Eurocode

MATERIAL	PROPERTY	TEST METHOD FOR BULK DENSITY	TEST METHOD FOR MAXIMUM DENSITY
Asphalt Concrete (BS EN 13108-1) (Reproduced from BS EN 13108-20TableB.1)	Void content including VFB and VMA for required void content $V_{max} \leq 7\%$ (prescriptive)	BS EN 12697-6 procedure B, in a saturated surface dry condition	BS EN 12697-5 procedure A, in water
	Void content including VFB and VMA for required void content $7 < V_{max} < 10\%$ (prescriptive)	BS EN 12697-6 procedure C, sealed with wax	
	Void content including VFB and VMA for required void content $V_{max} \geq 10\%$ (prescriptive)	BS EN 12697-6 procedure D, by dimensions	
Hot Rolled Asphalt (BS EN 13108-4) (Reproduced from BS EN 13108-20TableB.4)	Void content including VFB and VMA (prescriptive)	BS EN 12697-6 procedure A in a dry condition.	
Stone Mastic Asphalt (BS EN 13108-5) (Reproduced from BS EN 13108-20TableB.5)	Void content including voids filled with binder (prescriptive)	BS EN 12697-6 procedure B, in a saturated surface dry condition	

Percentage Refusal Density (PRD) in BS 598 – 104 was referred in some literature as the maximum density achieved in the laboratory to discuss the accuracy of some testing methods. This standard was withdrawn in 2008 and replaced by BS EN 12697-9.

Maximum theoretical density (MTD) or “Rice” density, is another important referencing density. It is based on the proportions and densities of aggregate and binder in the mixture. This is explained in the EN 12697-5 procedure C mathematical procedure.

2.2. NUCLEAR DENSITY GAUGE (NDG)

2.2.1. HISTORY

The first documented NDG use for measuring asphalt density was published in a conference in Chicago (Stephens 1964). The American Society for Testing and Materials (ASTM) developed standard D2950 in 1971 for testing asphalt densities using nuclear density gauges. It has incorporated a number of changes since, such as the addition of the precision and bias statement in the 2011 version (ASTM Committee D04.21, 2009). The latest version was published in 2014.

In the UK, the core method has been the dominant method of measuring asphalt density until 1982, when an official evaluation report on NDG was published by the Transport Research Laboratory (TRL). A working party was set up to assess and compare the NDG with traditional coring method in six motorway reconstruction contracts. The Campbell-Pacific MC-2 type NDG was used to measure densities adjacent to the core positions. Compliance checks using cores and NDG reached the same conclusion in 84% of the results. However, it was also recommended that coring shall be used to calibrate gauge measurements if in doubt. Comparative tests revealed that NDG readings were more variable than core densities. The gauge calibration temperature on the gauge calibration was reported to have minor impact on the readings along with the moisture condition of pavement surface. Overall, it was recognised that NDG could reduce the volume of testing on site and was a “simple, quick and non-destructive alternative method for measuring density” (TRRL 1982). This document also provided a procedure for using NDG. NDG was added to the later-published BS 4987:1988 as an alternative method for compliance checking on asphalt compaction. This served as relative readings compared to 93% PRD. This standard was replaced by BS 594987 in 2007 which included the informative protocol on calibration and operation.

2.2.2. COMPTON EFFECT AND NDG MODES

NDG works using the “Compton Effect”, also referred to as “Compton Scatter”. It is defined as “the scattering and increase in wavelength of an X-ray (or gamma-ray) photon on encountering an electron, with a partial transference of energy from the photon to the electron.” (Oxford English Dictionary online, 2016). Briefly, a small gamma ray is emitted from a radioactive source, transmitted through the pavement material and counted by the detector(s) on the other side of the NDG. The denser the pavement, the more energy consumed in penetrating the material and the count number. Conversely, a less well compacted pavement will be penetrated through more

easily so has a higher count reading. A direct correlation between the photon count and the material density can be therefore estimated (Troxler 2007).

There are two main testing modes – the backscatter mode and the direct transmission mode. The former is a non-destructive testing mode which measures density in layer thicknesses up to 100mm (see Figure 1). It comprises a radioactive source and two detectors, one at the centre and a second at one end. The latter incorporates an extendable source rod, which is placed through a pre-drilled hole to 300mm deep (see Figure 2). The density of the material up to 300mm thick can be measured. The testing mode “thin lift”, uses the same approach as the conventional backscatter mode but with different algorithm to account for the mat thickness. It is designed to measure the density of thin layers from 25 to 100 mm. It is available on some newer models, such as Troxler models 3450 and 4640 and CPN MC-3. The precision level of Troxler model 3450 reported by the Troxler Electronic Laboratories (2007) is summarised in Table 2 below, providing the standard deviation according to the lift thicknesses, reading durations and three testing modes – direct transition mode, backscatter mode and thin overlay mode. The precision level can be improved by increasing the duration of readings. The gauge measurements on thin layers appear to be less precise compared with thick layers. For example, according to Table 2, the gauge measurements of 1min reading duration in the thin overlay mode would produce a standard deviation of $\pm 16 \text{ kg/m}^3$ for a 25mm thick layer, whilst the measurements under the same condition would produce standard deviation of $\pm 8 \text{ kg/m}^3$ for a 63mm or 100mm thick layer.

Table 2: Troxler Model 3450 Precision (Unit: kg/m^3) (Troxler Electronic Laboratories 2007)

	DIRECT TRANS.	BACKSCATTER	THIN OVERLAY MODE			
Precision at	2000 kg/m^3		2240 kg/m^3			
Thickness	150 mm	100 mm	25 mm	50 mm	63 mm	100 mm
15 sec	± 5.2	± 16.0	-	-	-	-
1 min	± 2.6	± 8.0	± 16	± 10	± 8	± 8
4 min	± 1.3	± 4.0	± 8	± 5	± 4	± 4

Troxler Model 4640B thin layer NDG is designed to measure density of thin overlays without influence from the underlying materials. It comprises of two detecting systems – one reads the

backscatter from the upper layer only and the other one reads the backscatter from the lower layer. "System 1 is influenced by the uppermost portion of the material in greater proportion than is system 2. Therefore, their bulk density results can be combined numerically to calculate the overlay density." (Troxler Electronics, 2007). A similar precision level to the thin overlay mode of Troxler Model 3450 was reported by Troxler.

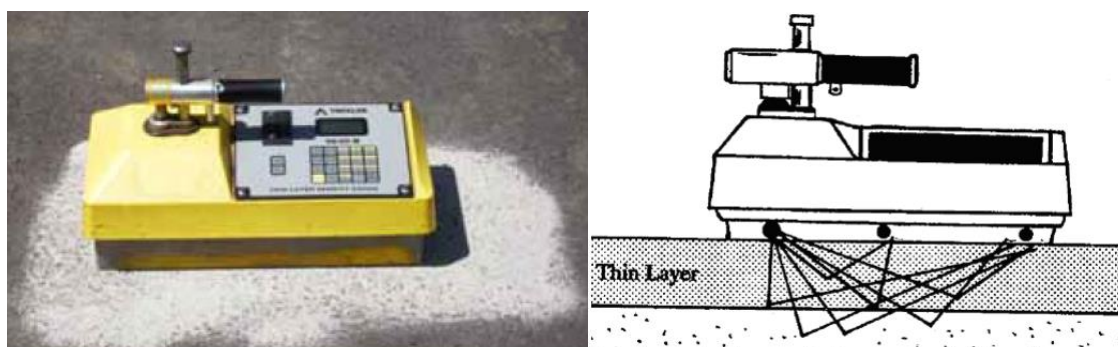


Figure 1 NDG Thin-Layer Asphalt Gauge in Testing Mode (VicRoads 2011)

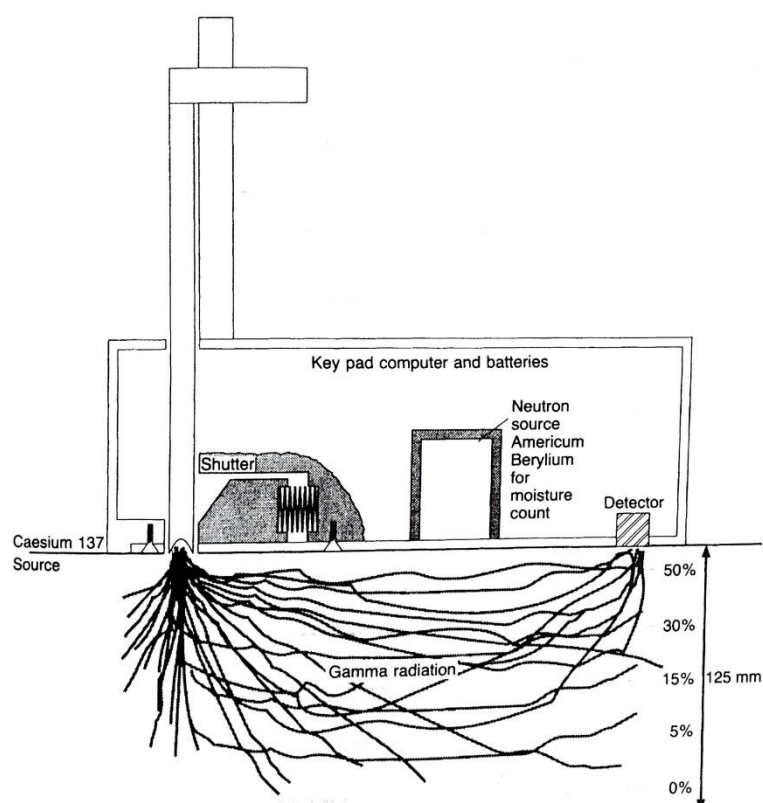


Figure 2 Schematic of Nuclear Density Gauge (Hunter 2000)

Due to the radioactive nature of the source, the NDG contains a heavy tungsten shielding block to minimise the risk of unprotected emission. The shipping weight of the device is typically 40kg including the case. There are stringent requirements on the store, transport and operation of the devices. All operatives must be trained and licensed. Warning signs and at least 2m clearance are required when it is in use. (Hunter 2000)

2.2.3. NDG EVALUATION

A number of studies were completed in 1970-1980s to evaluate the NDG and compare it with conventional coring with the intention to establish a correlation between them. Later, it became a standard method and a benchmark for assessing any other technologies for measuring asphalt density.

One of the early studies involved the evaluation of the density for road base macadam using NDG in eight UK construction projects (TRRL 1982). It was reported that the gauge readings were on average 2.5% lower than the core densities and were more variable. It was suspected that the gauge readings were more influenced by the density of the top 50mm under the backscatter mode for thin layers.

Burati and Elzoghbi (1987) compared three NDG readings with core densities on two projects. Three NDG devices from different suppliers were used - Troxler 3411-B, Seaman C-75BP and CPN M-2. The results presented significant variance among the gauges, as tabulated below. Lower results were reported by the NDG method than that by the core method, which was consistent with the findings from the TRL report. The NDG readings also appeared to be more scattered than the core readings. Similar findings were also reported by Choubane et al (1999) using five Troxler NDGs.

Table 3: Mat Density for core density versus NDG (Unit: kg/m³ (pcf)) (Burati and Elzoghbi, 1987)

	CORE	CPN M-2	TROXLER 3411-B	SEAMAN C- 75BP
Morristown – Mean	2430.0 (151.7)	2356.3 (147.1)	2381.9 (148.7)	2393.2 (149.4)
Morristown– Standard Deviation	48.1 (3.0)	65.7 (4.1)	64.1 (4.0)	73.7 (4.6)
Rochester – Mean	2414.0 (150.7)	2343.5 (146.3)	2365.9 (147.7)	2402.8 (150.0)
Rochester – Standard Deviation	33.6 (2.1)	59.3 (3.7)	51.3 (3.2)	46.5 (2.9)

A study funded by five US states and the Federal Highway Administration was completed to evaluate non-nuclear gauges for measuring asphalt density but also included the NDGs to provide baseline readings (Romero 2002). Each state had their own test protocols with slight variations. A statistical analysis using Student's t-testing, was completed to test the hypothesis that the difference between the core density under surface saturated dry condition according to ASHTTO T166 and NDG density is zero at 95% confidence level. This hypothesis was rejected. Statistical differences were recorded between the core density results and NDG readings in 53% of the projects in the 2000 field study and in 75% of the projects in the 2001, although this gave better correlation with core density than the non-nuclear gauges (Romero 2002). The average density measurements using core, NDG and non-nuclear gauge (PaveTracker) from five states in the 2001 field study are shown in Figure 3 below.

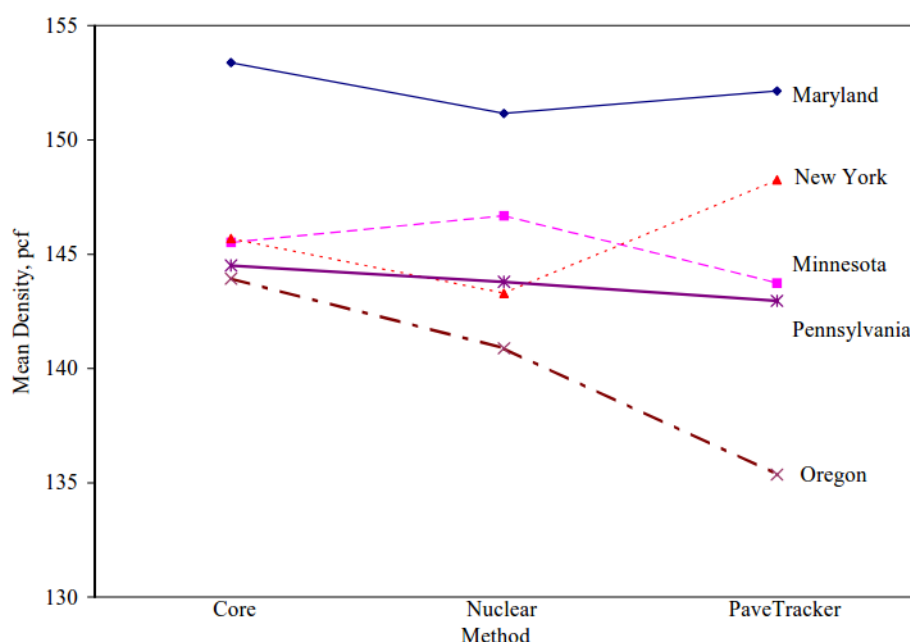


Figure 3 Average Density by Core, NDG & PaveTracker (Romero 2002)

Studies in six US States (California, Pennsylvania, Virginia, Nevada, Texas and Maine) concluded that the NDG should only be used for quality control rather than for quality assurance. Conversely in Connecticut, NDG was accepted for quality assurance and for payment certification. The Connecticut Department of Transportation (Conn DoT) performed a study in 2003 and 2004 aiming to develop a correlation between core density and NDG readings based on the data from seven projects (Padlo et al 2005). The target compaction thickness was 2 inches (51.6 mm) in all projects. The NDG results were found to be inconsistent from the six gauges used and also inconsistent with the core density results. The discrepancies between the core densities (vacuum sealed density in accordance with AASHTO TP 69) and the NDG measured densities varied from 0.3% to 1.2% of the maximum theoretical density (MTD), higher than 0.1% MTD, which was used by Conn DoT for acceptance of projects for payment. Core densities measured by three individual laboratories also had large variations. A linear regression analysis was performed to study the effect of mat thickness on the discrepancies. The local mat thicknesses obtained by the core depths ranged from 1.370 inches (34.8 mm) to 2.796 inches (71.1 mm). The linear regression results are summarised in Table 4. The negative slope values indicate that as the thickness of HMA mat increases the error in NDG density reduces. It was suspected that the NDG readings were affected by the underlying pavement density on thinner pavements. The correlation coefficient R^2 is very low indicating poor linear correlation between the mat thickness and the NDG errors. The effect of NDG orientation and pavement temperature on the density results was found not to be influential. Multiple readings at each test location were recommended. A comparison

between the thin-lift mode and backscatter mode was completed with the intention to identify a more accurate mode for thin pavement layers. However the review was inconclusive as insufficient evidence was collected to prove either of the modes was more accurate. A protocol for determining a correction factor between NDG and cores was developed for quality control. The percent compaction by cores was calculated and subtracted by the percent compaction by NDG. Any differences greater than 2% were considered to be caused by damaged cores and ruled out. The average of the remaining differences was deemed as the correction factor. It was suggested that the correction factors shall be project, mix and gauge specific and the NDG reading time shall be at least 1 minute to encourage better resemblance with the core density values (Padlo et al 2005). In addition, it was advised to establish a new correlation factor for any variation of more than 0.5 inches (12.7mm) in the target compaction thickness.

Table 4: Regression results of NDG error to mat thickness (Padlo et al 2005)

NDG	Y-INTERCEPT	SLOPE	R ²
CAP Lab	0.76	-0.94	5.6%
ConnDOT (990)	0.23	-0.26	0.0%
ConnDOT (354)	1.78	-0.99	4.8%
ConnDOT (17269)	1.52	-0.49	0.0%
ConnDOT (559)	1.83	-1.52	6.3%
Contractor (L540)	0.82	-0.57	0.7%

To produce the precision and bias statement in the ASTM D 2950 'Standard Test Method for Density of Bituminous Concrete in Place by Nuclear Methods', ASTM subcommittee D04.21 (2009) completed a study in 2009, involving four test strips of HMA with different aggregate grading, the nominal maximum aggregate size ranged from 9.5mm, 12.5mm, 19mm to 37.5mm. The mat thickness was 3in (76.2mm). Seven nuclear gauges were used in the study. The precision was assessed based on the repeatability and reproducibility in accordance with ASTM E691-99, 'Standard Practice for Conducting an Inter-laboratory Study to Determine the Precision of a Test Method'. "For repeatability, random variability inducing factors such as operator, equipment, calibration, and environment are kept reasonably constant – thus repeatability is often related to single-operator or within-lab variability of a testing or measurement process. Conversely, reproducibility includes variations in random variability-inducing factors and is often related to multiple operator or between-lab variability." The results are presented in Table 5 below, together with the results from a parallel study on electromagnetic gauges, which will be covered in the next

chapter. Higher precision levels are declared by the manufacturers. For example, the standard deviation of up to $\pm 16 \text{ kg/m}^3$ at an average density of 2240 kg/m^3 was specified for Troxler Model 3450 Thin-layer Mode & Model 4640-B based on 1min readings.

Table 5: Precision Statement for the nuclear gauges and Electromagnetic Gauges (Unit: kg/m^3) (ASTM Committee D04, 2009)

GAUGE	NUCLEAR DENSITY GAUGE	ELECTROMAGNETIC GAUGE
Average of Study Data	2199.0	2193.1
Repeatability Standard Deviation	66.5	52.4
Reproducibility Standard Deviation	66.5	52.4
Repeatability acceptable range of two test results (95% limit)	186.3	145.6
Reproducibility acceptable range of two test results (95% limit)	186.3	145.6

Bias is defined as follows – “The bias of values arising from a test method may be thought of as a consistent difference between the test values and some “true” or “known” value for the property being measured.” (ASTM subcommittee D04.21, 2009) Core density is considered as the best measure of the “true” density and is used to calibrate other measurement methods. But even the core density itself can vary when tested by different laboratories. Figure 4 below presented the core results in test strip 12 (12mm nominal maximum aggregate size) by laboratories A, B, C and D. The compaction effort (number of roller passes) was reduced from section 1 to section 7. Section 1 received the maximum number of roller passes and section 7 received the least. This was not obvious in the core density results. The density values within the same section presented large variations. Bias appeared to exist among the results from different laboratories – laboratory A generally presented the highest densities and laboratory D presented the lowest. The same trend was also reported in the other testing strips. Therefore, the following bias statement was issued in both the ASTM D2950 Standard Test Method for Density of Bituminous Concrete in Place by Nuclear Methods and ASTM D7113 Standard Test Method for Density of Bituminous Concrete in Place by the Electromagnetic Surface Contact Methods - “There is no consensus on the most accurate method to determine the values of density against which this test can be compared. Accordingly, a statement of method bias cannot be made.”

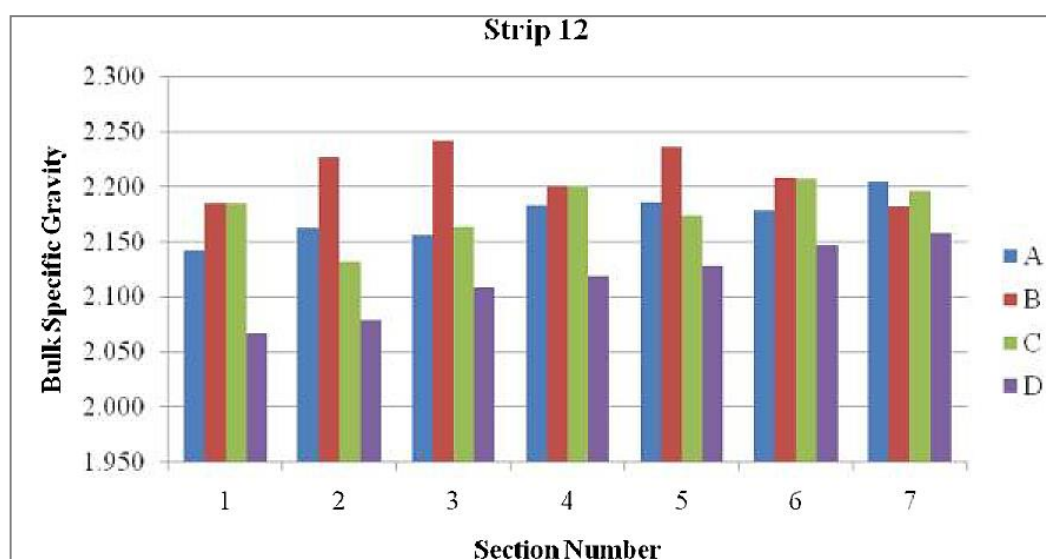


Figure 4 Bulk Specific Gravity Tested by Four Laboratories (ASTM Committee D04.21, 2009)

2.2.4. SUMMARY OF NDG METHOD

As an alternative to the traditional core method, NDG provides an effective quick assessment of the asphalt densities on site and enables in-progress corrections to the paving operation during construction. It has been widely accepted by the industry and put in practice over the last forty years. There are established standards and procedures for the calibration and operation. However, the NDG contains radioactive material which may be hazardous to health. Therefore there are rigorous requirements on the training for operators and licensing for the equipment. The use, keeping, transportation and disposal of the equipment must follow the relevant regulations and acts (HSE Ionising Radiation Information Sheet No. 3, 2002).

The following is a brief summary of the findings regarding the evaluation of the NDG from this literature review.

- The densities measured by NDG are lower and more variable than the core densities (TRRL 1982, Burati and Elzoghbi 1987, Romero 2002, Padlo et al 2005, Sargand, Kim and Farrington 2005, Ziari et al 2010).
- Both the backscatter mode and the thin-lift mode can measure a typical layer thickness between 25mm and 100mm. Mat thickness is taken into consideration in both modes but with different algorithms. No conclusive evidence is provided with regards to which mode performs better in measuring the asphalt density in thin pavement layers.

The density measured by the back-scatter mode and thin-lift mode was reported to be more influenced by the material at the top 50mm in thick pavement layers, whilst the density of thin pavement layers was reported to be affected by the substrate material. ASTM D2950 suggests “For lift thicknesses of 51 mm [2 in.] or less, the backscatter mode is suggested; for lift thicknesses greater than 51 mm [2 in.] the direct transmission mode is suggested. Thin lift gauges can be used for lift thicknesses up to 102 mm [4 in.]”.

Troxler Model 4640B thin layer nuclear gauge was claimed to have overcome the problem with erroneous results yielded from the underlying layers (Troxler Electronics, 2007). The application brief by Troxler (2007) provided a comparison study on an overlay with thickness ranging between 1-2in (25.4 – 50.8mm). A constant measuring thickness of 1.5in was programmed into both gauges. The overlay’s density was approximately 161.2 pcf and the underlying material’s density was approximately 133 pcf. As shown in Figure 5, the thin layer gauge provided more precise readings for all five overlay thicknesses than the non-thin-layer gauge. A study was completed in the state of Texas to evaluate the Troxler Model 4640 thin layer nuclear gauge and compare it with core method (Solaimanian, Holmgreen and Kennedy 1990). The average layer thicknesses from the seven projects varied from 1.1in to 1.5in (27.9mm – 38.1mm). The precision of the 4640 gauge was reported to be dependent on the mixture and better precision was achieved in limestone aggregate mixture than siliceous aggregate mixture. No comparison was made with other gauges.

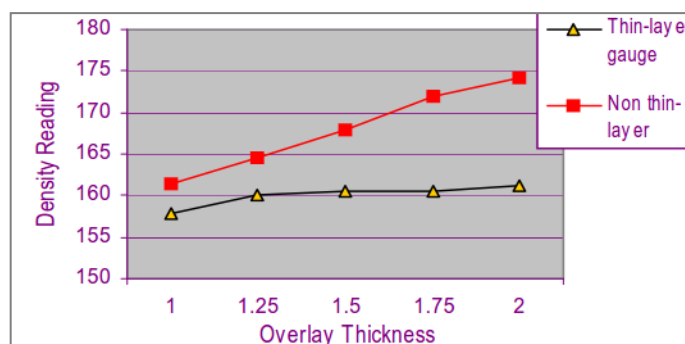


Figure 5 Troxler Model 4640B Thin Layer Gauge (Unit: inches and pcf for density and thickness respectively) (Troxler Electronics, 2007)

- The NDG readings may be influenced by environmental factors, material type, surface texture, aggregate types, HMA mat thickness, operator and nuclear gauge used, most of which can be compensated in a field calibration (Padlo et al 2005). Therefore, a project, mix and gauge specific calibration on a trial strip was recommended. Furthermore, Padlo et al (2005) also suggested a new correlation factor to be established when the target compaction thickness changes by 0.5in (12.7mm). The use of Leighton Buzzard sand was

recommended in TRL report 754 to fill the surface texture and ensure a firm contact between the gauge and the surface of the paving material for each measurement. ASTM D2950 also stressed the maximum contact is critical and shall be achieved by filling the voids by fine sand.

- No significant influence by temperature and moisture was reported for NDG measurement. It must be noted however, ASTM D2590 warns “Do not leave the gauge on a hot surface for an extended period of time. Prolonged high temperatures may adversely affect the instrument’s electronics. The gauge should be allowed to cool between measurements”.
- The precision level was assessed in a field study according to the repeatability and reproducibility in accordance with ASTM E691-99. Both the single-operator precision and multi-laboratory precision are stated in ASTM D2950.

3. DENSITY MEASUREMENT– OTHER METHODS

In addition to the above methods, BS 594987: 2015 Clause 9.4.2 and UK Manual of Contract Documents for Highway Works (MCHW) Volume 2 Notes for Guidance on the Specification for Highway Works Clause NG929 (08/08) also permit the use of alternative indirect density measuring devices other than nuclear density gauges. The calibration and operation protocol is provided in BS 594987 Annex I for all indirect density gauges including NDGs. The following chapter will introduce other technologies, beginning with capacitive electromagnetic method, which is receiving more industry recognition. Other technologies are also available, such as ground-penetrating radar, step-frequency radar, ultrasound technology and automated field density prediction. However, most of these are still at the research stage.

3.1. CAPACITIVE ELECTROMAGNETIC METHOD – PQI & PAVETRACKER

3.1.1. HISTORY

The first non-nuclear density gauge used to measure HMA density was made available by TransTech Systems Inc. in 1998. The very first model, called Pavement Quality Indicator (PQI), later referred to as “PQI-100”, was reported to have “serious problems when the moisture is present in the mixture”. To address the problem, the moisture level is measured and recorded in the later model, PQI-300, through the lag or phase angle in the electrical signal. This value is displayed as “H2O” reading on the PQI interface and contributes to the built-in corrective algorithm to compensate for the moisture effect. Conflicting views were taken by different authors on its performance (Romero 2000, Henault 2001, Romero 2002). TransTech made further improvements on the PQI models – PQI 302 were available in 2005 and PQI 303 in 2007. The latest model, PQI 380, as shown in Figure 6, features a user friendly interface and an advanced GPS system.

PaveTracker by Troxler is another electromagnetic-type device but uses slightly different technology based on the “chemical composition per unit volume” (Troxler 2013). The photos of the the latest model, PaveTracker™ Model 2701-B Plus, are shown in Figure 7. The measuring depth is up to 51mm.

There are published standards for testing density of asphalt using electromagnetic gauges in the United States – ASTM standard D7113 and AASHTO T 343-12.



Figure 6 Model 380 PQI by TransTech
(<http://www.transtechsys.com/products/index.php>)



Figure 7 Model 2701B PaveTracker Plus by Troxler
(<http://www.troxlerlabs.com/Portals/0/Troxler%20Documents/Marketing%20Documents/PaveTracker%202701-B/2701BSS102015.pdf>)

3.1.2. DIELECTRIC CONSTANT

HMA is a non-conductor or dielectric. When a dielectric is placed in an electric field, the strength of the field reduces. The amount of the strength reduction can be characterized by a material property called the dielectric constant. The dielectric constant of HMA depends on its composition.

A homogeneous HMA typically ranges from 2.5 to 3.2. The dielectric constant for water ranges from 4 to 88 (Mason 2008). The PQI and PaveTracker operate in the same principle by assessing the change in an electric field to determine the dielectric constant of the tested material. Then the density can be calculated by comparing the dielectric constants with a material with a known density. A schematic figure of the PQI is shown in Figure 8. If the HMA contains more air and has low density, the dielectric constant would be lower, and vice versa. Based on the above constants, it is possible that the presence of moisture may misleadingly increase the density readings. This is confirmed in many studies. (Henault 2001, Romero 2002, Mason 2008)

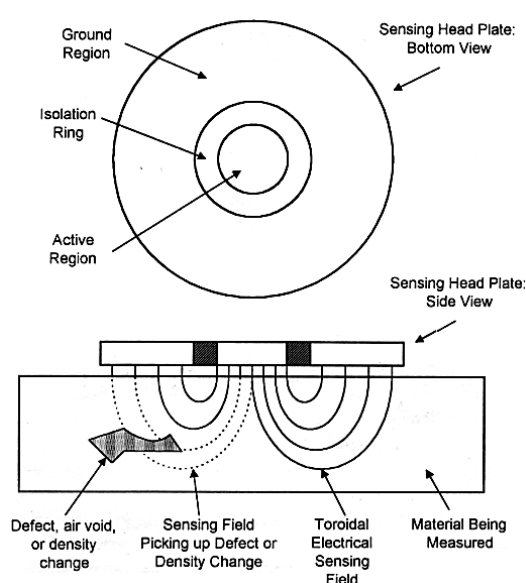


Figure 8 Schematic of PQI Sensing Plate (NCHRP-IDEA, 1999)

3.1.3. EVALUATION OF PQI AND PAVETRACKER

In the last 20 years, US highway authorities funded independent research to evaluate performance of electromagnetic gauges for measuring HMA densities. Most studies accept PQI as a quality control measure but do not recommend it for quality assurance testing. Trial sections are recommended to enable calibration. (Romero et al 2002, Williams et al 2007)

Romero (2000) completed a well-designed laboratory test to evaluate the performance of PQI-300 under various conditions by varying nominate maximum aggregate size (NMAS), aggregate source, temperature and moisture. It was suggested that changes in NMAS may be adjusted by offsets in the calibration process. Changes in aggregate grading, aggregate source and temperature appeared to produce different correlations between the PQI and asphalt density. Therefore, mixture-specific calibration incorporating both proportionality (slope) and offset was

recommended. The PQI manual (2003) details the procedure for both offset and slope calibrations. However, the slope calibration was highlighted for factory use only. The experiment used H₂O display on the PQI devices to monitor moisture changes and came to a conclusion that as long as the moisture is kept constant and relatively low (below 5% H₂O number in the experiment), PQI-300 can be used for quality control. As presented in Figure 9 below, when the slab density was relatively high, the signal reading for samples with internal moisture was not deviated from the reading for samples in dry condition. But when the internal moisture is relatively high (H₂O number $\geq 5\%$), the difference in the signal reading increased significantly. Hence, the problem with PQI density still remained.

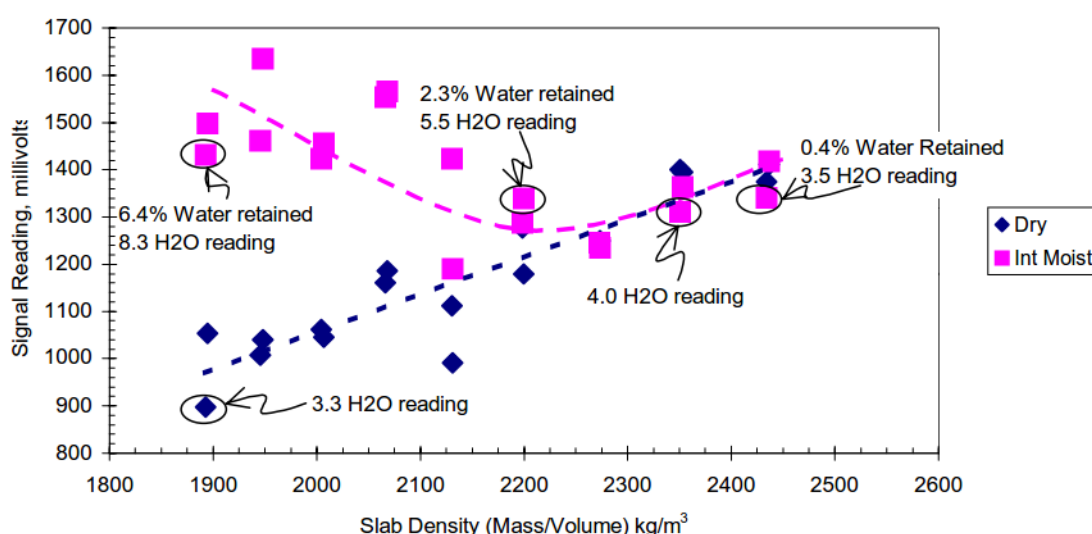


Figure 9 Effect of Internal Moisture on PQI-300 Electrical Signal Reading (Romero 2000)

Henault (2001) applied PQI-300 in ten paving projects in Connecticut to evaluate its field performance. The lift thickness was 50mm in eight projects and 37.5mm and 75mm in the other two projects. Poor correlation with an average correlation coefficient R^2 value of 0.28 was reported between PQI density obtained in the field and core density according to AASHTO T-166. Henault suggested this might be due to the moisture introduced into the HMA rolling operations. Although much of the surface moisture evaporated, there was still evidence of vapour in the hot mat. The threshold of 5% H₂O number reported in Romero's report (2000) was exceeded. Henault stressed that the H₂O < 5% were very difficult to achieve in a field condition even after wiping the pavement surface and PQI sensor disk with dry cloth. Only 7 out of 100 H₂O values were below 5%. Hence, PQI was not considered reliable for either quality control testing or quality acceptance testing.

Following the promising results achieved in the lab, Romero (2002) completed a field evaluation in 2001 and 2002, involving 6 states and 114 projects in total. However, the field results were less

assuring. The testing regime was tailored to suit individual participating states and different procedures were followed. The field evaluation in 2001 concluded “the factors shown in the laboratory study to affect the PQI-300 readings cannot be successfully controlled in the field. The PQI-300 could not be used to measure pavement density with any level of reliability.” The 2002 field study further affirms that neither PQI-300+ (“+” indicates an improved gauge over the regular PQI-300) nor the PaveTracker were suitable for quality acceptance. Both gauges were outperformed by NDG in terms of precision. A large variation was reported in the PQI and PaveTracker readings, as shown in Figure 3 and Figure 10. They were considered more suitable for measuring relative density and identifying areas with insufficient compaction due to their ease of use. It was recommended to develop a standard procedure incorporating the operating procedure and calibration method. A specification for PQI was developed by Pennsylvania Department of Transportation (PennDOT) and included in the report as a guide.

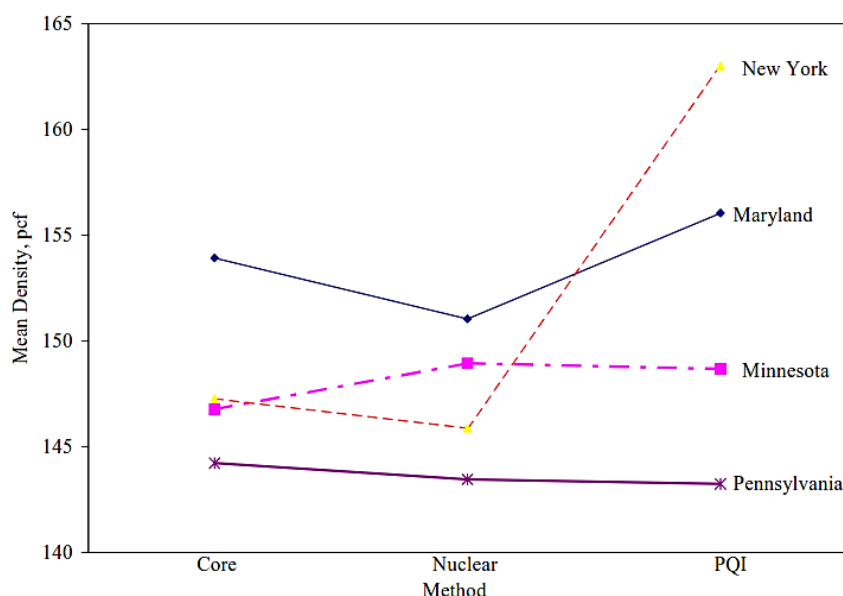


Figure 10 Average Density by Core, NDG & PQI Gauge (Romero 2002)

Sargand, Kim and Farrington (2005) performed a field study to evaluate the performance of the PQI Model 300 and PaveTracker. The PaveTracker was also evaluated under the laboratory condition by changing the following factors – temperature, moisture, aggregate size, sample area and mat thickness. It was found that the gauge reading was decreased by 16kg/m^3 on average for coarse mixes and 24kg/m^3 for fine mixes when the temperature was dropped by 50°C . Water was sprayed on the surface of the dry specimen to assess the effect of surface moisture. Gauge readings decreased by 110kg/m^3 on average for coarse mixes and 430kg/m^3 on average for fine mixes with the application of 0.49kg/m^2 surface moisture. Figure 11 below presents the correlation between core density and gauge density for four surface moisture conditions – surface dry, surface

moisture level I ($\leq 0.098\text{kg/m}^2$), surface moisture level II ($0.098\text{kg/m}^2 - 0.24\text{kg/m}^2$) and surface moisture level III ($0.24\text{kg/m}^2 - 0.49\text{kg/m}^2$). Furthermore, the samples were submerged in water for 24 hours and towel dried before taking measurement to assess the effect of internal moisture. Unlike the surface moisture, the gauge density increased with the internal moisture. Similar findings to Romero's study (2000) was revealed – the increase in the gauge readings was more pronounced in asphalt with low densities whilst the gauge readings for high density asphalt were not so sensitive to internal moisture, as presented in Figure 12 below. Two mat thicknesses (38mm and 55mm) and three base materials (wood, HMA and concrete) were introduced in the lab study to assess the effect of the substrate and mat thickness on the PaveTracker measurements on thin asphalt layers. The measuring thickness for the gauge used in the study was 44.5mm. It was concluded that when the mat thickness was less than the gauge measuring depth, the gauge reading was affected by the underlying material at a rate of 0.03 kg/m^3 per 1 kg/m^3 of base material density. Negligible influence from the substrate was noted when the gauge measuring depth was larger than the mat thickness. In the field study, the PQI results was found to be in better agreement with the core results than the results from nuclear gauges or PaveTracker, on the condition that a daily mix-specific offset was applied as recommended by the manufacturer. Hence PQI-300 was considered reliable for assessing the asphalt density as a quality control and quality assurance measure.

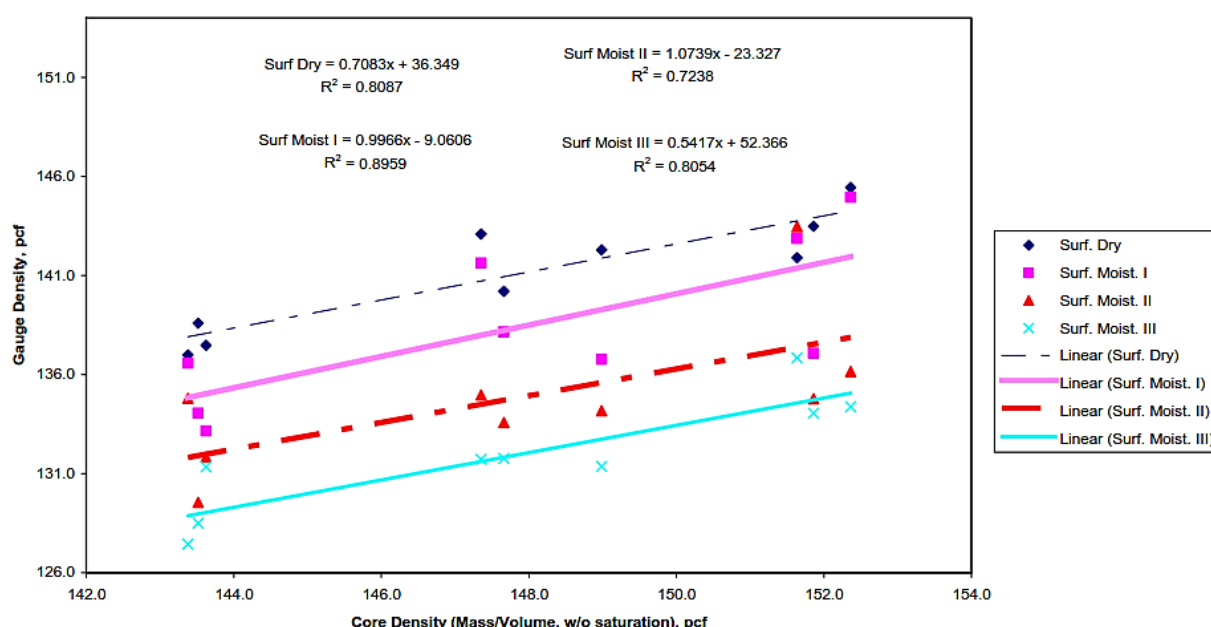


Figure 11 Effect of Surface Moisture on the Relationship between PaveTracker Gauge Density and Core Density for Fine Mixture (Sargand, Kim and Farrington 2005)

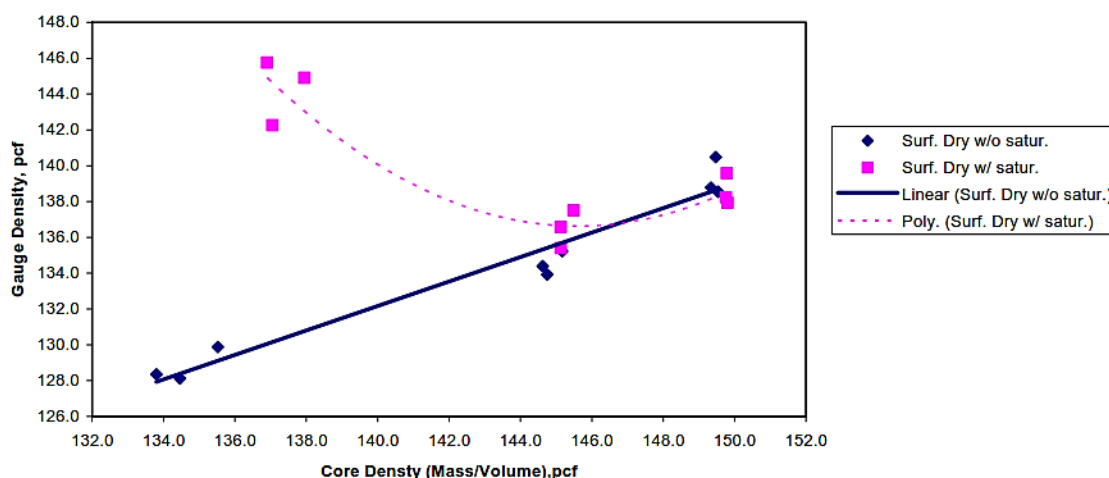


Figure 12 Effect of Internal Moisture on the Relationship between PaveTracker Gauge Density and Core Density for Fine Mixture (Sargand, Kim and Farrington 2005)

A similar evaluation was completed by Williams et al (2007) both in the laboratory and field. The field data were collected at 15 sites in the State of Iowa involving 7 contractors. Both the PQI and the PaveTracker managed to detect density changes after roller passes, which qualified them for quality control testing. The lab data suggested significant differences between densities tested in dry/wet conditions, as a result of the effect of moisture. Several mix-and project-specific factors were deemed influential, such as contractor, aggregate type and binder content. Therefore, a test strip was recommended for calibrated on a project, mix and gauge – specific basis for quality control and quality assurance testing. The authors also suggested future evaluation could consider the use of newer gauge models and increasing the gauge testing frequency.

A small-scale field evaluation by Ziari et al (2010) drew some positive conclusions towards the use of PQI for density measurement. The test section was 70m long by 3.65m wide with 60 testing positions. The PQI-301 was calibrated with cores extracted from the same section at 5 locations. As a result, a calibration factor of 171kg/m³ was identified and added to the mean of PQI readings. The PQI densities appeared to match the core densities with the probability of 95%, more reliable than the NDG. It was concluded that PQI was reliable to determine the asphalt density for both quality control and quality assurance.

Allen, Schultz and Willett (2003) compared the results from a NDG (Troxler Model 4640B Thin Layer Nuclear Gauge), two PQI-300 gauges (Transtech Model PQI 300) and cores in a resurfacing project in Kentucky. The resurfacing was composed of 0.5in (12.7mm) Superpave surface with a PG76-22 binder. The total compacted lift thickness was 1.5in (38.1mm). Manufacturers' calibration procedures were followed. To calibrate the nuclear gauge, four readings were taken at each of the

three core locations. To calibrate the PQI, a minimum of five single readings using a clockwise motion were taken at each of the five test locations within a 10-foot area. One of the PQI results had similar means to core density and 88% overlap in the distribution, whilst the NDG and the other PQI varied, as shown in Figure 13. The gauge results were more scattered than the cores. The authors suggested PQI was only suitable for quality control on HMA paving mats. The key influential factor moisture was not addressed in the paper.

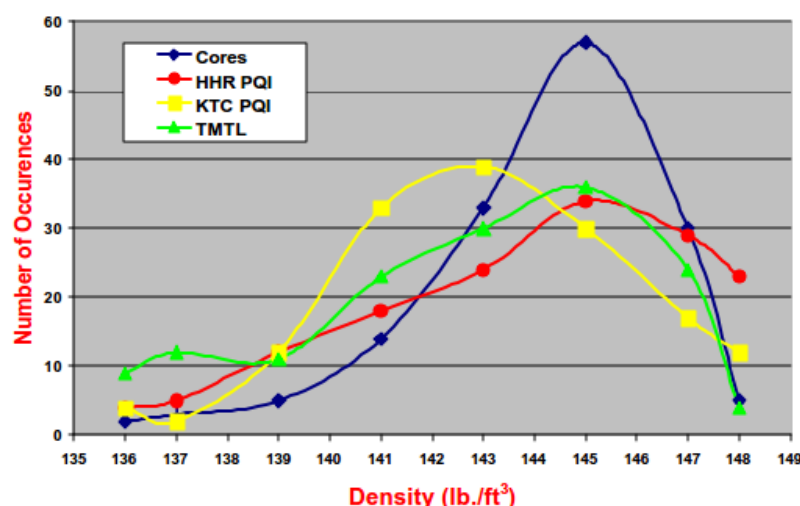


Figure 13 Distribution of Density Values (Allen, Schultz and Willett 2003)

It is worth mentioning that a cost comparison was completed by Pennsylvania State Innovations Council and reported a saving of \$50,318 over 5 years in training and operation by replacing nuclear gauges with PQI system (Glagola 2003).

To produce the precision and bias statement in the ASTM D7113 Standard Test Method for Density of Bituminous Paving Mixtures in Place by the Electromagnetic Surface Contact Methods, ASTM subcommittee D04.21 (2009) completed a study in 2009, involving four test strips of HMA with different aggregate grading, the nominal maximum aggregate size ranged from 9.5mm, 12.5mm, 19mm to 37.5mm. The mat thickness was 3in (76.2mm). Ten electromagnetic devices – six from TransTech Systems and four from Troxler Labs, were used in the study. The precision was assessed based on the repeatability and reproducibility in accordance with ASTM E691-99, Standard Practice for Conducting an Interlaboratory Study to Determine the Precision of a Test Method. The results are presented in Table 5 above, together with the results from the parallel study on nuclear gauges. It is noted the averaged density of the study data measured by electromagnetic devices is very close to those measured by nuclear gauges. And the standard deviations for electromagnetic devices are less than the ones for nuclear gauges. Hence, the results produced by the electromagnetic devices were less variable than the ones produced by the

NDG. As explained in Section 2.2.3, no bias statement was issued as no “true” or “known” value of pavement density is available. Higher precision levels are declared by the manufacturers. For example, the standard deviation of up to $\pm 3.2\text{kg/m}^3$ was specified for PaveTracker™ Model 2701-B Plus.

3.1.4. SUMMARY OF USING ELECTROMAGNETIC DEVICES

Electromagnetic devices offer a quick, economic, non-radioactive and non-intrusive solution to measure HMA density. Comparing to NDG, it is lightweight and easy to transport. It requires less extensive and periodical calibration (Williams 2007). However, conflicting conclusions were drawn from various studies regarding the reliability of these devices.

The following is a brief summary of the findings regarding the evaluation of the electromagnetic devices from this literature review.

- The electromagnetic gauge readings are mainly influenced by moisture, operators and calibration. It is more likely to obtain reliable readings in a controlled environment, such as laboratory condition (Romero 2000) or small-scale field condition (Ziari et al 2010), with low moisture level, single operator and strictly-followed mix- and gauge-specific calibration.
- The typical measuring thicknesses of PQI and PaveTracker are 25-100mm and up to 51mm respectively. When the mat thickness was less than the measuring depth, the PaveTracker reading was reported to be the composite density of the HMA and the underlying material, as a result of the influence from the substrate material. None of the literature reviewed so far provides a detailed study on the effect of the substrate on the measurement of asphalt density using PQI.
- PQI 301 Manual (TransTech 2000) warns no readings shall be taken where there are signs of excessive surface moisture and states accurate readings can be obtained if the H₂O readings displayed are low and consistent. But it does not provide the limit of H₂O value for a valid reading. Romero (2000) indicated a threshold value of 5%, which was claimed to be difficult to obtain on site by Henault (2001). It is more likely to obtain accurate results if the moisture level is low, although the latest models of PQI and PaveTracker claim to be insensitive to moisture and no correction factor required. ASTM D7113 also appears to consider the presence of roller water is acceptable. Further investigation may be required.
- No significant influence by temperature was reported for PQI and PaveTracker. But ASTM D7113 suggests “The calibration must be completed on the mat within the mat temperature range that will be encountered during subsequent testing.” To achieve the best results, it is advised to avoid surface with temperature extremes.

- A mixture specific calibration incorporating both offset and slope was recommended (Williams et al 2007). The offset calibration shall be completed on site by operators. The procedure provided in ASTM D7113 may be used jointly with manufacturers' guidance. The slope calibration shall be completed by manufacturers at least once a year.
- The precision level was assessed in a field study according to the repeatability and reproducibility in accordance with ASTM E691-99. Both the single-operator precision and multi-laboratory precision are stated in ASTM D7113.
- The effect of magnetic fields on the electromagnetic gauges is unclear. Therefore it might be reasonable to avoid using the devices near power lines.
- The gauges used in most of the literature are the early models. Improvements have been made to the devices over the years. Further evaluation using the newer models may be required to verify the current conclusions drawn based on the old models.

3.2. ELECTROMAGNETIC WAVE-BASED METHOD – RADAR SYSTEMS

Ground-Penetrating Radar (GPR) has been used in pavement engineering to measure layer thicknesses and detect pavement distresses since 1970s. It was first considered as an approach to measure asphalt density and void content by Al-Qadi (1992), which was followed by the development of a computer program to predict asphalt densities and water contents (Lytton 1995). Building on these, more studies were completed in recent years. But until now, it is still at the research stage and not ready for the industry yet.

The GPR method is electromagnetic-wave-based. Short electromagnetic pulses are emitted from an antenna and penetrating through the pavement. Echoes created at pavement surface and internal inhomogeneity are reflected back and captured by a data acquisition system. The dielectric constant can be estimated based on the amplitude and phase of the reflected signals. Once the correlation between the dielectric constant of an asphalt mixture and its density is determined, the asphalt density can be predicted through a GPR survey. There are two established correlations based on electromagnetic mixing theory – Complex Refractive Index Model (CRIM) and modified Bottcher model, as demonstrated in Eq. 1 and 2 respectively. The latter assumed the air particles and aggregates in the mixture were in spherical shape.

Al-Qadi et al (2011) further improved the modified Bottcher model by the introduction of a shape factor, u , to account for non-spherical inclusions and established the Al-Qadi Lahouar Leng (ALL) Model, shown in Eq. 3. This was validated using in-service pavement data. The pavement structure is composed of 50mm thick new asphalt overlay with five different mixtures over an old asphalt overlay and concrete pavement. Steel slags were introduced in two of the mixes: The

fibre/slag mix contained 20% slags and the friction mix contained 36% slags. Both the GPR results and the nuclear density gauge results were compared with the core densities under surface saturated dry condition. A better precision of in situ density using GPR was achieved than that using NDG in the mixes without slags, as shown in Figure 14. The average prediction errors varied from 0.5% to 1.1%. In the mixes with steel slags, the average prediction errors of GPR results were 1.9% and 2.9%, higher than the results using NDG. It was suspected that the high dielectric constant of metal and its random distribution in the mixes might have contributed to the errors. Two calibration cores were recommended to produce a reliable ϵ_b .

$$G_{mb} = \frac{\sqrt{\epsilon_{AC}} - 1}{\frac{P_b}{G_b} \sqrt{\epsilon_b} + \frac{(1 - P_b)}{G_{se}} \sqrt{\epsilon_s} - \frac{1}{G_{mm}}} \quad (1)$$

$$G_{mb} = \frac{\frac{\epsilon_{AC} - \epsilon_b}{3\epsilon_{AC}} - \frac{1 - \epsilon_b}{1 + 2\epsilon_{AC}}}{\left(\frac{\epsilon_s - \epsilon_b}{\epsilon_s + 2\epsilon_{AC}}\right) \left(\frac{1 - P_b}{G_{se}}\right) - \left(\frac{1 - \epsilon_b}{1 + 2\epsilon_{AC}}\right) \left(\frac{1}{G_{mm}}\right)} \quad (2)$$

$$G_{mb} = \frac{\frac{\epsilon_{AC} - \epsilon_b}{3\epsilon_{AC} - (u - 2)\epsilon_b} - \frac{1 - \epsilon_b}{1 - (u - 2)\epsilon_b + 2\epsilon_{AC}}}{\left(\frac{\epsilon_s - \epsilon_b}{\epsilon_s - (u - 2)\epsilon_b + 2\epsilon_{AC}}\right) \left(\frac{1 - P_b}{G_{se}}\right) - \left(\frac{1 - \epsilon_b}{1 - (u - 2)\epsilon_b + 2\epsilon_{AC}}\right) \left(\frac{1}{G_{mm}}\right)} \quad (3)$$

Where:

- G_{mb} – bulk specific gravity of asphalt mixture;
- G_{mm} – maximum specific gravity of asphalt mixture;
- G_b – specific gravity of binder;
- G_{se} – effective specific gravity of aggregate;
- G_{sb} – bulk specific gravity of aggregate;
- P_b – binder content;
- ϵ_b – dielectric constant of binder;
- ϵ_{AC} – dielectric constant of asphalt mixture;
- ϵ_s – dielectric constant of aggregate
- u – shape factor

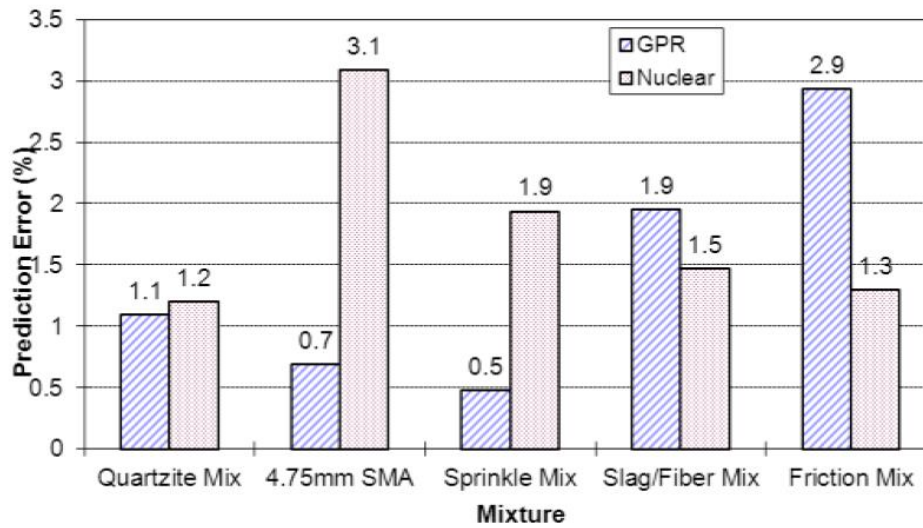


Figure 14 Comparison of prediction error for HMA density using GPR and NDG

The study examined the temperature effect on the dielectric constant measured by GPR and concluded it was insignificant. Being an electromagnetic based method, it is expected that the moisture condition still plays an important role in providing accurate results. However, the moisture effect was excluded in the study and dry condition was assumed.

The dielectric constant of a thin single-lift asphalt pavement surface was estimated by the surface-reflection method, as illustrated in Eq. 4, where the dielectric constant of the first layer $\epsilon_{r,1}$ was estimated based on the amplitude of the surface reflection A_0 and the amplitude of the incident GPR wave A_p , which is the amplitude of the reflection over a copper plate placed on the pavement surface. This dielectric constant was then applied in Eq. 5 to predict the layer thickness d_1 , where t_1 is the two-way travel time of the GPR signal within the surface layer and c is the speed of light, $3 \times 10^8 \text{ m/s}$. Leng (2011) suggested this method provided good performance in his study.

$$\epsilon_{r,1} = \left(\frac{1 + \frac{A_0}{A_p}}{1 - \frac{A_0}{A_p}} \right)^2 \quad (4)$$

$$d_1 = \frac{ct_1}{2\sqrt{\epsilon_{r,1}}} \quad (5)$$

Leng's (2011) back-calculation approach to derive the dielectric constant of aggregate was criticised by Pellinen et al (2015). The authors stated that, since this value was the dominant factor

for dielectric value of asphalt mixture and it varied for different aggregates, this back-calculation approach “may lead to large errors in assessing pavement density”. Fauchard et al (2013) measured the dielectric constant of aggregate using cylindrical resonant cavities and reported a variation from 4.5 to 7.7 for the tested samples of sandstones, quartzite, granite, limestone and basalt etc. Not only the aggregate types but also same aggregate from different quarries appears to have large variations in their dielectric constants. Pellinen et al (2015) further questioned the calibration of GPR based on one core only whilst the antenna covered a larger footprint of 300mm by 300mm (referred to as “volume element”). Attempts were made to quantify this variability by introducing a representative volume element (RVE). It was reported that the bulk property void content measured by GPR technique cannot be reliably calibrated using one core only and a sensible RVE was still to be determined.

Fauchard, Beaucamp and Laguerre’s case study (2015) suggested that pavement thickness may be estimated with sufficient accuracy using the GPR system based on one or two calibration points. A 3% error on the thickness measurement was suggested for the GPR system based on the mean amplitude. In other words, for an HMA layer of 50mm the thickness measurement would be 48.5mm. However, in the case of density measurement or compaction assessment, the time drift and signal instability in GPR may cause significant errors. The specific gravity measured at one location during one hour’s time can vary between 2.24g/cm³ and 2.42g/cm³, as shown in Figure 15. The density could be considerably overestimated due to this time drift effect. Step Frequency Radar (SFR) based on a similar principle of electromagnetic wave propagation, was considered more suitable. It is composed of a Vector Network Analyser (VNA) and an ultra-wide band antenna, which generates a step-by-step sinusoidal electromagnetic signal over a selected frequency. Figure 15 shows the variation in the estimated density at a given location during one hour’s time by the two radar systems. SFR appears to be more stable and less variable than GPR (Fauchard, Beaucamp and Laguerre 2015).

Other practice includes combining GPR with paver-mounted infrared bar system to provide contractors with a simultaneous response of the temperature and compaction (Sebesta and Scullion, 2007).

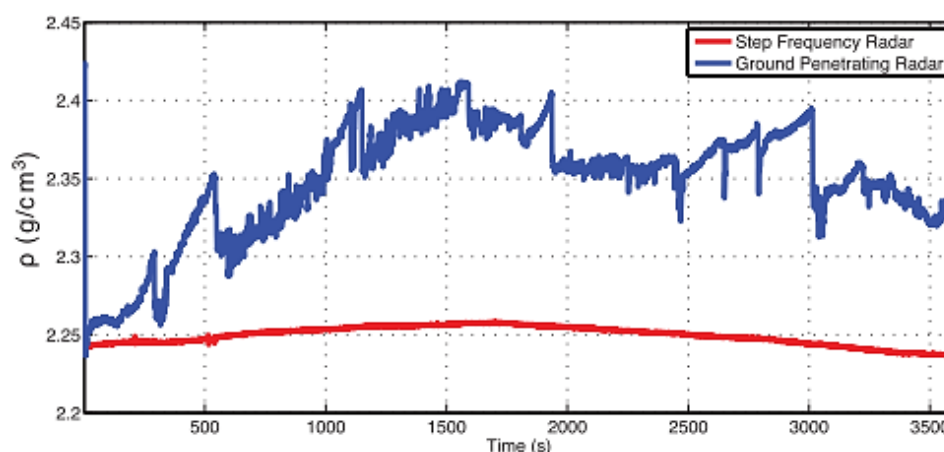


Figure 15 Density by GPR & SFR (Fauchard, Beaucamp and Laguerre 2015)

Overall, the radar systems have the advantage of providing full coverage of the area with continuous, efficient and non-intrusive density measurement. However, there are some obstacles to overcome before this may be adopted by the industry in field density measurement.

- Moisture is a major cause of inaccurate density assessment with all the electromagnetic-based technologies. The presence of water in the pavement has a strong influence on the dielectric constant measurements, and hence the density. The precision of the radar systems in evaluating asphalt density is subjective to testing under dry condition, which is a major limitation of this method. Al-Qadi et al (2011) also suggested a feasibility study to predict the asphalt density and moisture content simultaneously using the GPR system.
- The dielectric constant of aggregate has an influential role in the evaluation of asphalt density using radars. Depending on the aggregates' mineral composition, porosity, moisture content and frequency, a variation of 4.5 – 7.7 was reported (Fauchard et al 2013). With the increasing use of recycled aggregate in road construction, a practical and reliable procedure for evaluating the aggregate dielectric constant is required to encourage accurate prediction of asphalt density.
- The dielectric constant of a thin single-lift layer was obtained by the amplitude of the surface reflection and the amplitude of the signal reflection over a copper plate. It is understood that the layer thickness was not accounted for in the prediction of asphalt density in thin layers using the GPR method (Al-Qadi et al 2011, Leng 2011 and Pellinen et al 2015). This may need some justification. Alternatively, if a reasonable layer thickness can be estimated, the dielectric constant may be derived based on the two-way travel time of the GPR signal within the surface layer using Eq. 5. Hence, the layer thickness is considered in the prediction of asphalt density using this procedure.

- The signal instability in GPR can cause large variation in density readings over time. This appears to be an issue to be addressed. Step frequency radar was reported to provide more stable readings.
- It is demonstrated that this method has the potential to predict asphalt densities more efficiently compared to current discrete measurement methods. However, further studies are required to evaluate its performance considering the following factors, such as moisture, aggregate types and sources, binder aging effect, testing frequency and the models used. A standard calibration procedure and the precision level are still to be developed and defined.

3.3. ULTRASOUND METHOD

Ultrasound technology has been used to evaluate basic properties of solids for years by transmitting high frequency sound energy through the material in the form of waves. Until recently, it was used to evaluate the dynamic modulus of asphalt mixture with reasonable precision. (Leng, 2011). Dunning, Karakouzian and Dunning (2007) piloted the use of non-contact ultrasound technique to determine the bulk specific gravity of hot mix asphalt in a feasibility study. It was reported that the specific gravity of the asphalt mixture was highly related to the decay rate of energy as it passed through material. This study laid a foundation for density measurement using the ultrasound technology in the future. However, the correlation was not defined and a considerable amount of work is required before the application in the industry can possibly be considered.

3.4. ROLLER MOUNTED ASPHALT DENSITY DEVICES

The need of a practical approach to record and monitor the real-time compaction process provoked the technology of “Intelligent Compaction (IC)”. It was originally developed in 1980s for soil and sub-base and then adapted for asphalt pavement in 1990s. The IC system comprises of conventional vibratory rollers equipped with instruments which are able to measure, record and display the compaction effort. The commonly attached instruments include: GPS to locate the individual roller on the project, accelerometers attached close to the drums to measure the vertical acceleration of the roller frame, infrared temperature sensors attached on the front and the rear of the roller to measure the surface temperature of the mix and interface display panels to record and display the compaction progress with the aid of a processing software. It enables the roller operator to track the roller passes and make adjustment to the compaction patterns. Colour-coded mapping can be displayed for real-time surface temperature, compaction pattern and compaction measurement value (CMV), which is a dimensionless number based on the surface stiffness.

Further improvement was made to the IC system to convert the compaction energy to material density enabling the monitoring of real-time density distribution. In 2015, Volvo announced their new roller model – density direct as shown in Figure 16, which was claimed to be able to convert the vibrations to density readings using a proprietary artificial neural network. It was tested on full depth and overlay asphalt pavements at several sites in the United States and was reported to “produce a density calculation that is accurate to within 1.5 percent of core sampling” (Volvo 2015). No further details have been disclosed on the technology.



Figure 16 Intelligent Compaction System by Volvo (2015)

TransTech (2016) also announced a new roller mountable density measurement device PQI 380 On-the-Run (OTR), which is due to be released in 2017. It is a “noncontact, on-the-run, real time system for monitoring the density of HMA during road construction”. Instead of interpreting the vibration motion to asphalt densities, the OTR measures the density using a laser unit fixed to the base of the plant. Operators can monitor the compaction process by the real-time density measurements displayed on a windows tablet during rolling. No further information has been published so far.

Although the IC system has the potential to provide the most efficient, simultaneous, continuous and extensive density measurement on site; it has some flaws that can lead to erroneous results. The vibration and compaction motion applied on the pavement surface is likely to travel much deeper than the compacting layer. The response from the pavement reflects the full depth of the compaction impact. Therefore the influence from the substrate material on the density measurement is almost certain and would need to be considered, especially for a thin surface course. Kassem et al (2012) pointed out that a number of factors should be addressed through the

calibration process and fed into a software programme which could potentially interpret the compaction behaviour into the material density. The following factors were considered by Kassem et al (2012) – mix surface temperatures and the temperature gradient through depths, roller passes, compaction energy distribution along a roller drum, roller compactor types and operation modes. The abovementioned issue with lift thickness and underlying material was not discussed in the proposal.

The emerging technology on roller mounted asphalt density devices has the potential to become the future trend in non-destructive density measurement. However, it still faces some challenges such as the effect of the underlying material and lack of guidance on the calibration and precision level. Therefore, it is considered that there is not sufficient evidence to prove its suitability to use on TSCS at this stage.

4. RECOMMENDATIONS

The reviewed methods are summarised in Table 6 below according to their attributes to help selecting the appropriate methods for in-situ trials. The core density is the only direct measurement of the density and is used as the calibration reference. Hence it is not included in the comparison.

The electromagnetic wave based method, GPR and SFR, and the ultrasound method are still at the research stage and in need of further investigations. The intelligent compaction system has been used for quality control for over 20 years, but its application in density measurement is very recent and has not been fully comprehended by the industry. Although the roller compactor with the ability to measure asphalt density is now available commercially, there are questions regarding the soundness of the results. Further evaluation is required to decide the measuring layer thickness and the measurement precision. The nuclear gauge method and capacitive electromagnetic method have been established for in-situ density measurements for long time. There are extensive standards and guidance for their calibrations, operations and precision levels in the ASTM documents. The British standards also offer some guidance. According to the literature, the sensitivity to moisture of PQI and PaveTracker was high and their precision levels were more acceptable for QC than for QA. However, early models of devices were used in most of the literature. New models are expected to perform better. More options are provided for various lift thicknesses in new models. Based on the above, it is recommended to further explore the potentials for using non-nuclear capacitive electromagnetic equipment, such as PaveTracker, for QA/QC in situ density assessments of TSCS.

Table 6: Summary Table

	NUCLEAR DENSITY GAUGE	PQI	PAVETRACKER	GROUND PENETRATION RADAR & STEP FREQUENCY RADAR	ULTRASOUND	ROLLER MOUNTED DEVICES
Source	Radioactive	Electromagnetic	Electromagnetic	Electromagnetic (wave based)	Sound Wave	Various
Calibration	General calibration according to ASTM D7759 and D7103	Core calibration according to ASTM D7113	Core calibration according to ASTM D7113	Core calibration	Core calibration	Core / NDG calibration
Repeatability and Reproducibility Standard Deviation (kg/m ³)	66.5 (ASTM D2950)	52.4 (ASTM D7113)	52.4 (ASTM D7113)	Not available	Not available	Not available
Layer Thickness (mm)	25 – 100 (thin layer modes and thin layer gauges available)	Typically, 25 – 100	Up to 51	Not available	Not available	Not available
Moisture Sensitivity	None or minor impact	Yes, but “not affected by moisture” stated in PQI380 specification	Yes, but “no moisture correction needed” stated in Model 2701-B specification	Yes	Yes	Unknown
Temperature Sensitivity	Minor impact	Minor impact, but needs calibration	Minor impact, but needs calibration	Minor impact	Minor impact	Yes, recorded

Specification / Guidelines	ASTM D2950 BS 594987	ASTM D7113 AASHTO T 343-12	ASTM D7113 AASHTO T 343-12	None	None	None
Research or QA/QC Tools	QA/QC	QA/QC	QA/QC	Research	Research	QC
Substrate Conditions	Thin layer gauge designed to avoid substrate influence	Unknown	Unknown	Unknown	Unknown	Unknown
Approximate Cost	\$6,000	£9,500 for TransTech PQI 380	\$28,000			
Weight (kg)	13.5 – 17	6.44	5	N/A	N/A	N/A
Instant Measurement	1 – 4 minutes	5 seconds	2 seconds	Instant	Instant	Instant
Special Training	Yes	No	No	No	No	No
Other Limitations	Licensing	Cannot use near electromagnetic force fields, e.g. high voltage power line or large metal objects.	Cannot use near electromagnetic force fields, e.g. high voltage power line or large metal objects.	Testing in dry condition only	Limited information on density measurement	Lack of published data

5. TESTING

5.1. LABORATORY LARGE SCALE PAVEMENT TRIALS

5.1.1. ARRANGEMENT

Pavement test sections were constructed in a full-size indoor Test Pit Facility (TPF) at AECOM's laboratory in Nottingham. A 10m by 3.8m test area was laid with 60mm thick binder course with 4% air voids achieved by standard compaction using a Bitelli – BB621e 'mini paver' and a roller compactor. The surface course was laid in six sections in the testing area following three design thicknesses (30mm, 40mm and 50mm) and two target air voids (4% and 8%). The general arrangement in the pavement testing facility is shown in Figure 17. The compaction and density measurements are shown in Figure 18 –Figure 20.

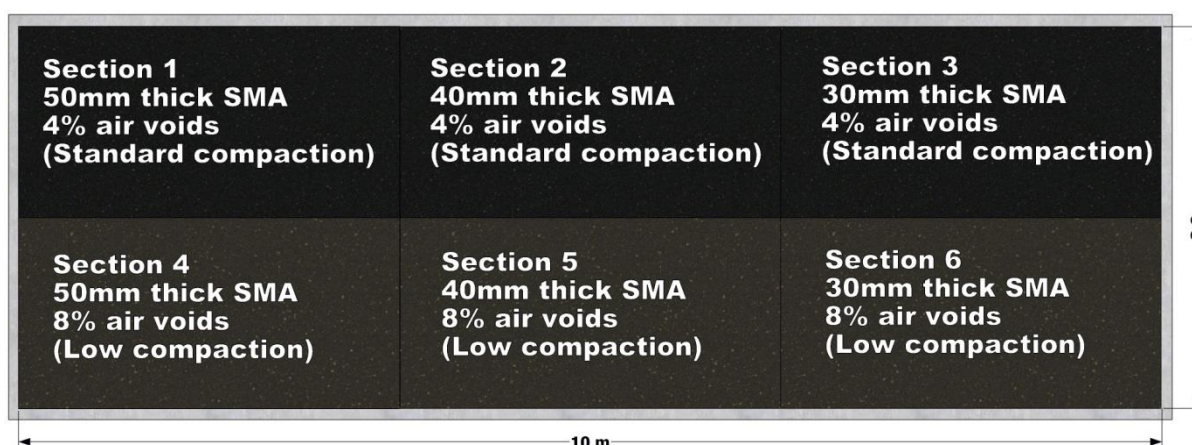


Figure 17 Laboratory Testing Arrangement

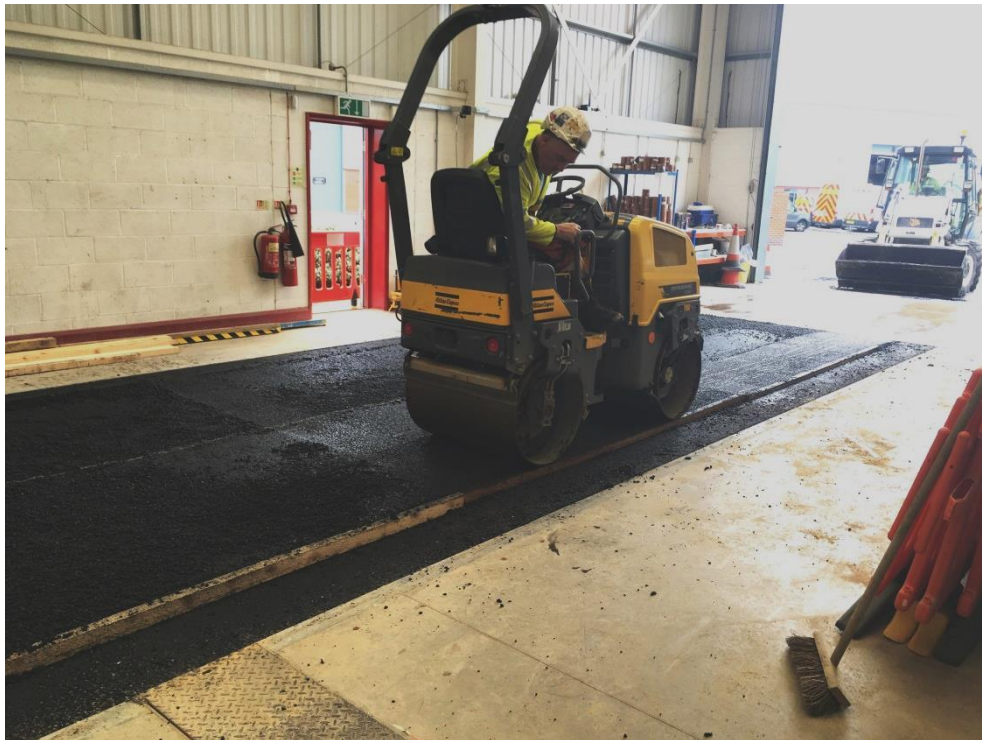


Figure 18 Surface Course Compaction

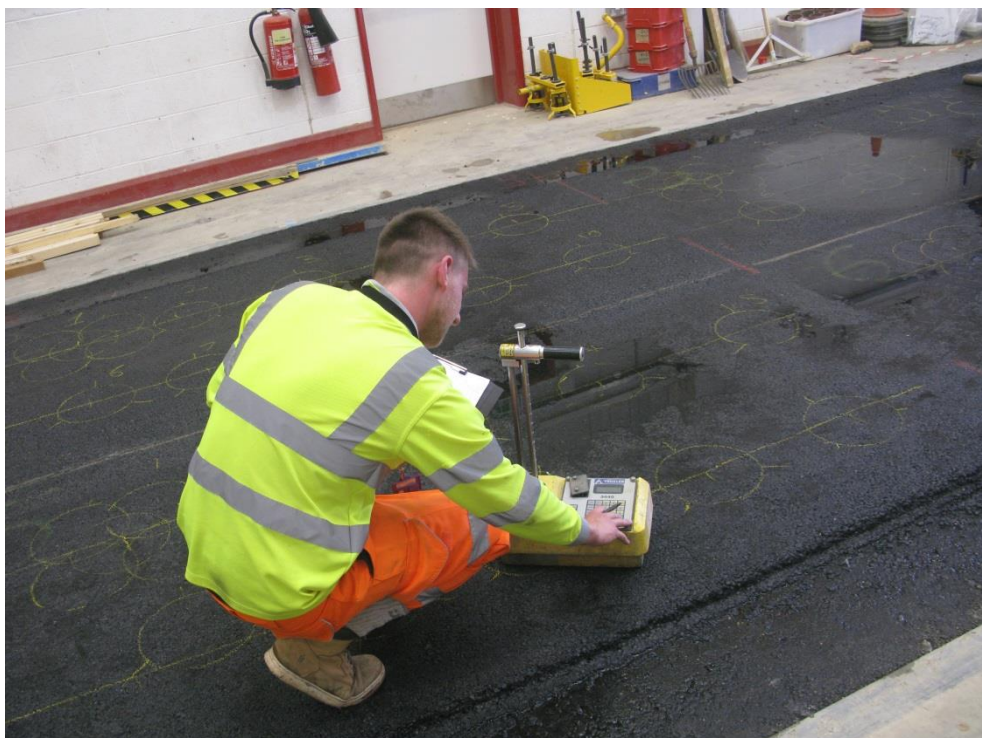


Figure 19 Density Measurement using a Nuclear Density Gauge (NDG)

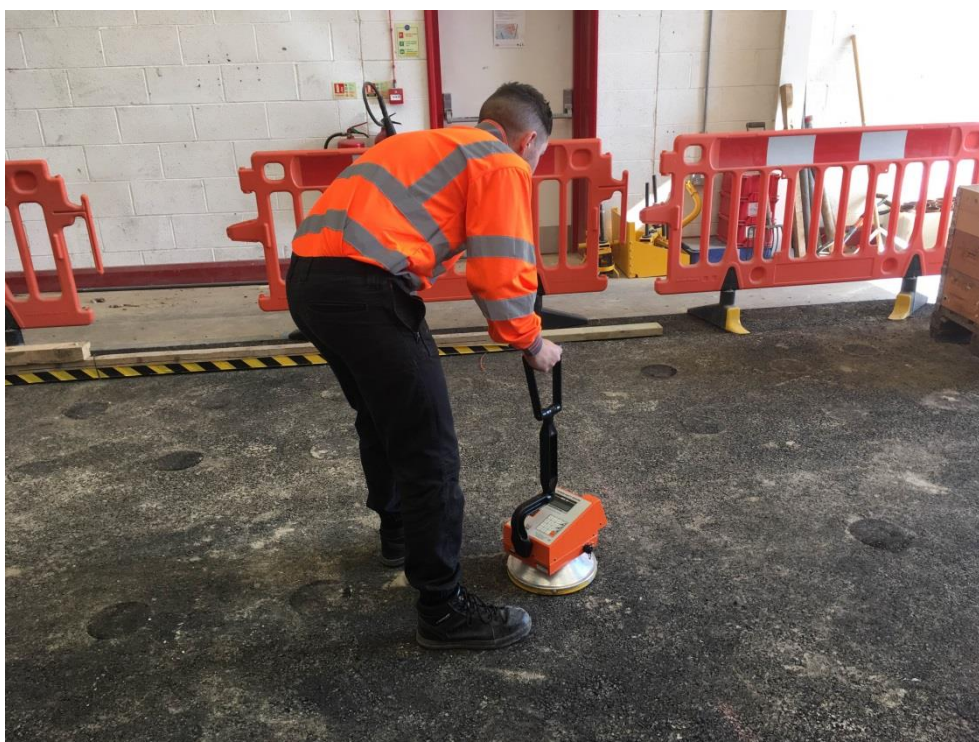


Figure 20 Density Measurement using a Pavement Quality Indicator (PQI)

5.2. MATERIALS

One standard mix was developed for the surface course according to the Thin Surface Course Systems (TSCS) in the Manual of Contract Documents for Highway Works Volume 1 (MCHW1). The mix was described as generic SMA 10 surf 40/60. Prior to laying the surface course, the substrate was installed, it comprised AC20 dense 100/150 over standard Type 1 foundation. A sketch of the pavement structure is shown in Figure 21. The aggregate used in the laboratory are common in pavement construction so that the results may be applicable in most conditions.

50, 40 & 30mm	SMA10 surf 40/60 - Standard & Low Compaction
60mm	AC20 dense bin 100/150
Foundation	Compacted Aggregate Base – Type 1

Figure 21 Schematic Pavement Structure

5.3. DEVICES

Two types of indirect density gauges were used to take measurements. They are Nuclear Density Gauge (NDG 3440 model by Troxler) and Pavement Quality Indicator (PQI 301 by TransTec Systems), as shown in Figure 19 and Figure 20. The NDG was pre-calibrated by the operating contractor, whereas the PQI was pre-calibrated by the manufacturer. The NDG measurements were completed in accordance with Appendix 2 in TRL 754 and BS 594987 Annex I. The PQI

measurements were completed in accordance with the manufacturer's guidance and BS 594987 Annex I.

The density readings were taken at ten pre-marked testing locations in each section, as depicted in Figure 22. The first location was designed as a calibration point where the PQI readings were taken at the centre and at 2, 4, 8 and 10 o'clock positions, using the "average mode". The subsequent PQI readings were taken at the centres only using the "single mode". The PQI was turned 120 degrees in order to obtain 3 readings per location. The NDG measurements were completed by a licensed contractor. One NDG reading at the centre of each location was obtained for each testing scenario. Cores were taken from the centre of each marked locations. Core bulk density were taken according to BS EN 12697-6: 2012 Procedure B and C and core maximum density and air voids according to BS EN 12697-5: 2009 Procedure A and BS EN 12697-8: 2003.

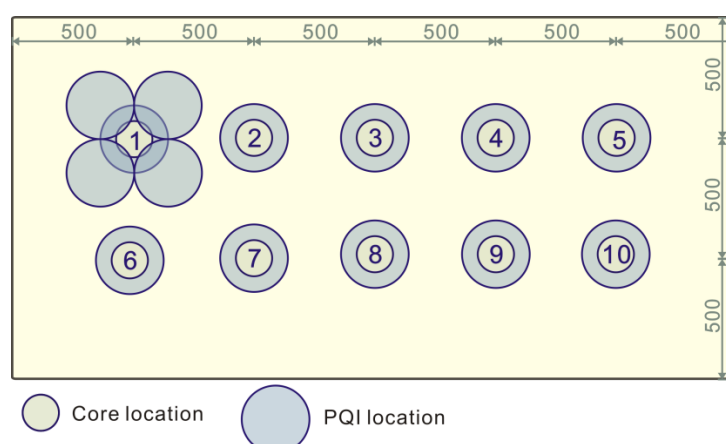


Figure 22 Individual Section Test Arrangement

Both NDG and PQI readings were taken under two moisture conditions as follows.

- Ambient dry condition (Dry)
- Surface wet condition (Wet): The trial area was soaked and covered with saturated hessian for a few hours. Excess water on the surface was mopped off before taking gauge readings.

The NDG and PQI readings under the dry and wet conditions are hereafter abbreviated as "NDG Dry", "NDG Wet", "PQI Dry" and "PQI Wet".

Three design thicknesses of 30mm, 40mm and 50mm and two levels of compaction efforts were applied to the testing area to study their influence on the accuracy of the density measurements. However, it is proved difficult to achieve a uniform thickness/compaction in a section. Hence, core

thicknesses and densities at each location are considered in the following analysis, rather than the design thicknesses and target air voids.

5.4. BASIC DATA

The basic gauge readings are summarized in Table 7 and Figure 23. The primary findings on the raw data are as follows.

- Core densities are highly concentrated with a small standard deviation of 22kg/m³. The mean of the core densities will fall within the narrow range of 2372 – 2383 kg/m³ 95% of the time.
- There is larger spread of results for NDG and PQI readings.
- The data sets are roughly symmetrical apart from the slight right-hand skew on PQI results.
- Both NDG and PQI readings in the wet condition exhibit higher means and higher variability than those in the dry condition.
- PQI readings may underestimate the density.
- The outliers are noted in four datasets. They cannot be removed without good reason and hence, they are retained throughout this analysis.

Table 7: Summary of Core Densities and Gauge Readings (Unit: kg/m³)

	CORE DENSITY	NDG DRY	NDG WET	PQI DRY	PQI WET
N	60	60	60	60	60
Median	2378	2375	2456	2169	2302
Mean	2378	2384	2464	2181	2307
Standard Deviation	22	48	77	68	103
Confidence Level ¹	6	12	20	18	27
95% Confidence Intervals ²	2372 – 2383	2372 – 2397	2444 – 2484	2163 – 2199	2280 – 2333

¹ Confidence level about the mean: the probability that the mean falls within a specified range of values.

² 95% Confidence Intervals about the mean: a range of values so defined that there is a 95% probability that the mean lies within it.

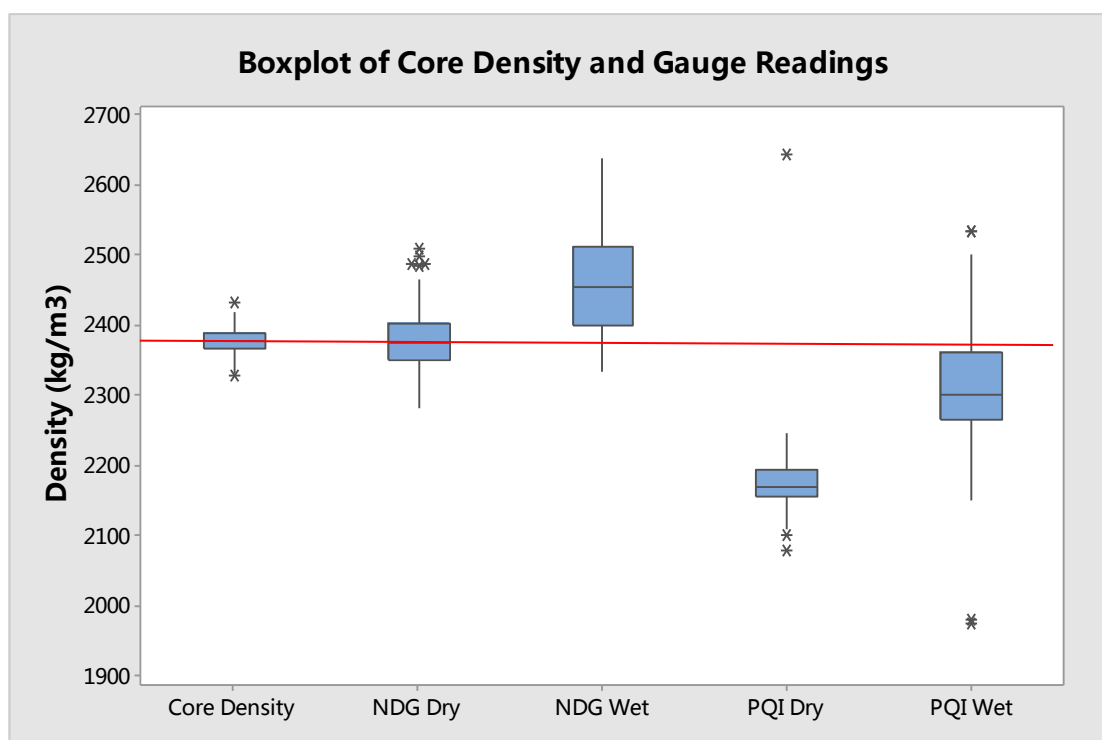


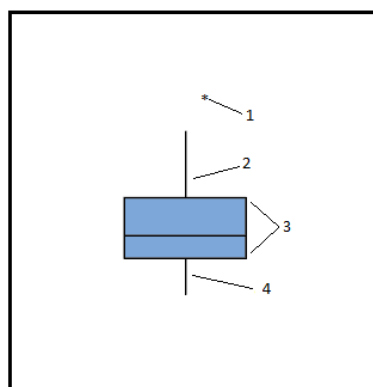
Figure 23 Boxplot of Gauge Readings³

5.5. CALIBRATION

5.5.1. STANDARD, GUIDANCE AND MANUFACTURER'S RECOMMENDATION

TRL 754 recommends taking a NDG reading on a standard block usually made of magnesium or aluminium, before and after the day readings are taken. BS 594987 Annex I provides the protocol for calibrating and operating indirect density gauges. It suggests each gauge shall be calibrated to produce a relationship between gauge readings and core density. AASHTO T343-12 also suggests calibrating the electronic surface contact device at 1-5 test locations on HMA mat prior to taking more measurements.

³ Legend for boxplot (Minitab 17 Help)



- 1 **Outlier (*)** – Observation that is beyond the upper or lower whisker
- 2 **Upper whisker** – Extends to the maximum data point within 1.5 box heights from the top of the box
- 3 **Interquartile range box** – Middle 50% of the data
 - Top line – Q3 (third quartile). 75% of the data are less than or equal to this value.
 - Middle line – Q2 (median). 50% of the data are less than or equal to this value.
 - Bottom line – Q1 (first quartile). 25% of the data are less than or equal to this value.
- 4 **Lower whisker** – Extends to the minimum data point within 1.5 box heights from the bottom of the box

The PQI manual (2003) provides the calibration procedure based on a linear correlation with core density, involving calibrating both the gradient and the intercept, referred to as “slope” and “offset” as depicted in Figure 24. The slope calibration is for factory use only and the offset calibration is completed on site by the operator.

The NDG had been pre-calibrated according to the operating contractor. The PQI had also been pre-calibrated by the manufacture before the laboratory trial. This chapter examines how the on-site calibration may affect the results. In a project, the gauge measurements may be taken in a trial section, where cores are extracted at the same locations. The difference between the measurements and the core densities (“offset”) can be worked out before any gauge measurements in the permanent works. PQI even allows for the offset input in its calibration menu, so that the displayed readings would be the calibrated. However, in this laboratory trial, the pavement must remain intact until all the readings were taken due to the repetitive readings at the same locations. The cores were extracted after completing all the measurements. Hence, the “offset” was set to zero in PQI and the “on site” calibration was processed afterwards, as detailed in the following paragraphs.

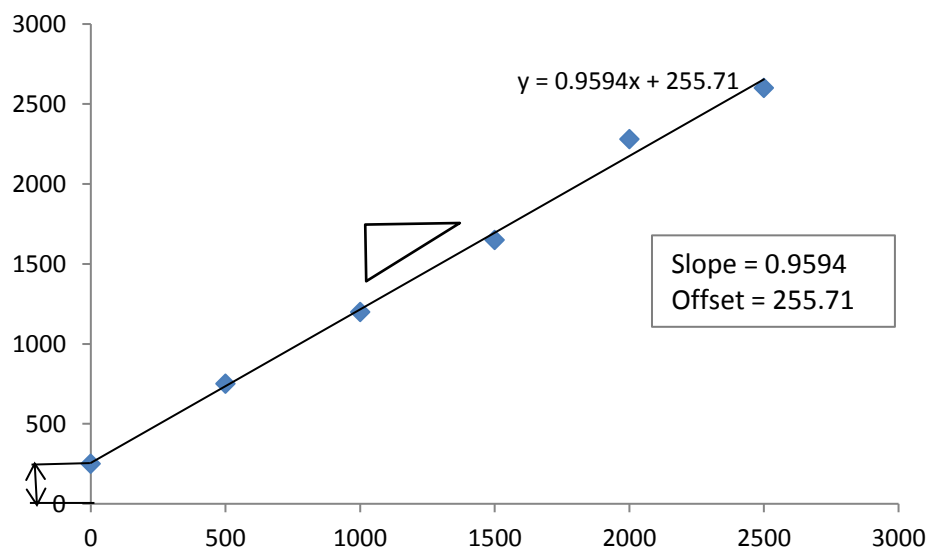


Figure 24 A Random Example of Slope and Offset

5.5.2. EFFECT OF CALIBRATION

The first test location in each section was designed to be a calibration point, such as the first point in Section 1 (1.01), the first point in Section 2 (2.01) and 3.01, 4.01, 5.01 and 6.01. Hence, the data may be calibrated against any one of them because each reading is independent. In other words, a reading is not affected by the preceding readings. This simulates the initial calibration in a trial section before taking the readings in the permanent works on site.

Figure 25 shows the boxplot of the calibrated data of NDG Dry and PQI Dry. The PQI reading at the calibration point 3.01 appears to be an outlier with an exceptionally high density of 2829 kg/m³. There appears to be no good reason to exclude this data point in the following analysis but clearly, calibrating against this point would skew the data. Solely for better visualization, Figure 26 plotted the dataset again excluding the PQI density at location 3.01 or the calibrated data using this point. The red line represents the mean of core density. It is found that the data distribution is not affected by the calibration process. But the mean of the calibrated data may present some variations from the mean core density, as a result of reading at the calibration point. This implies the precision of the PQI and NDG readings to the core density may be questionable. In other words, PQI and NDG may not be suitable for quality assurance, but they may still be tenable for quality control. This is further discussed in Section 6.5.

Regular re-calibration may help to mitigate the problem. If the readings are calibrated for each section, i.e. the subsequent readings are calibrated against the first reading in each section, the calibrated data appears to be more reasonable as shown in Figure 27. Note the outliers in PQI measurements are caused by calibrating the subsequent readings in Section 3 using the reading at 3.01. In addition, a reasonable spread of core densities would be support a better calibration. BS 594987 suggests “A suitable density range to produce results with the necessary spread of values has been found to be at least 4%.” This is not achieved in this project. The overall spread of core density is just 4.5% and the data spread in the calibration process is far less.

To closely simulate a site condition, the calibration using the very first reading 1.01 is applied for the following analyses.

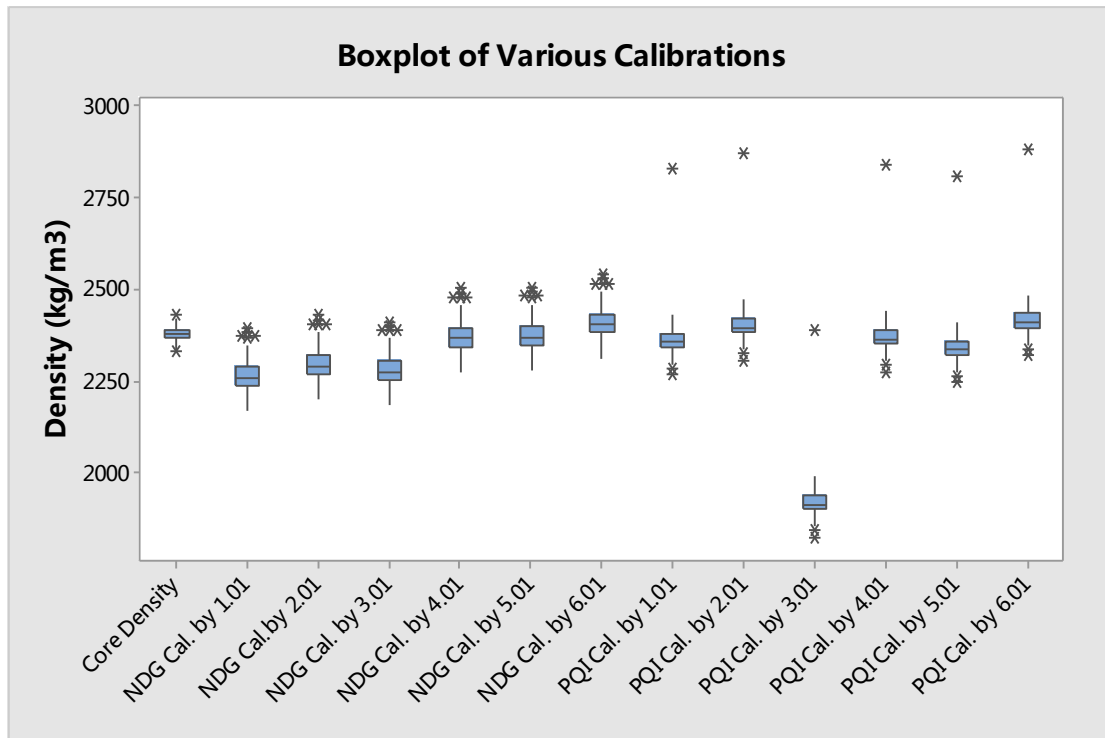


Figure 25 Calibration by One Location

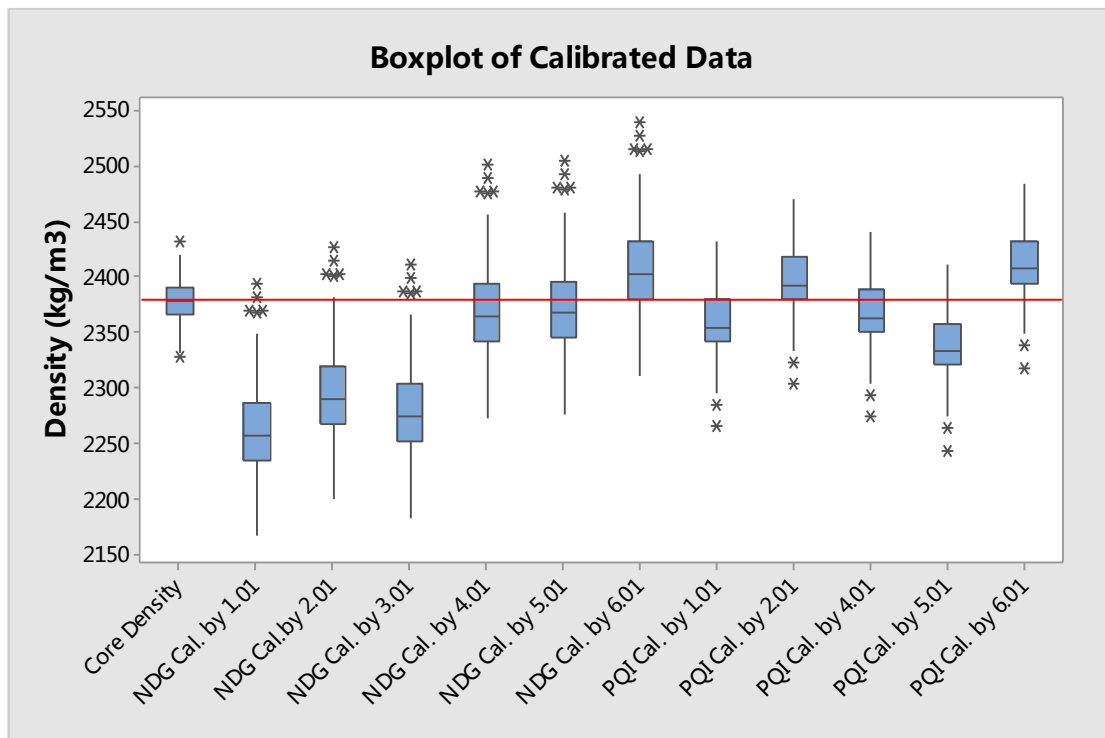


Figure 26 Calibration by One Location (Without the Outlier at Location 3.01)

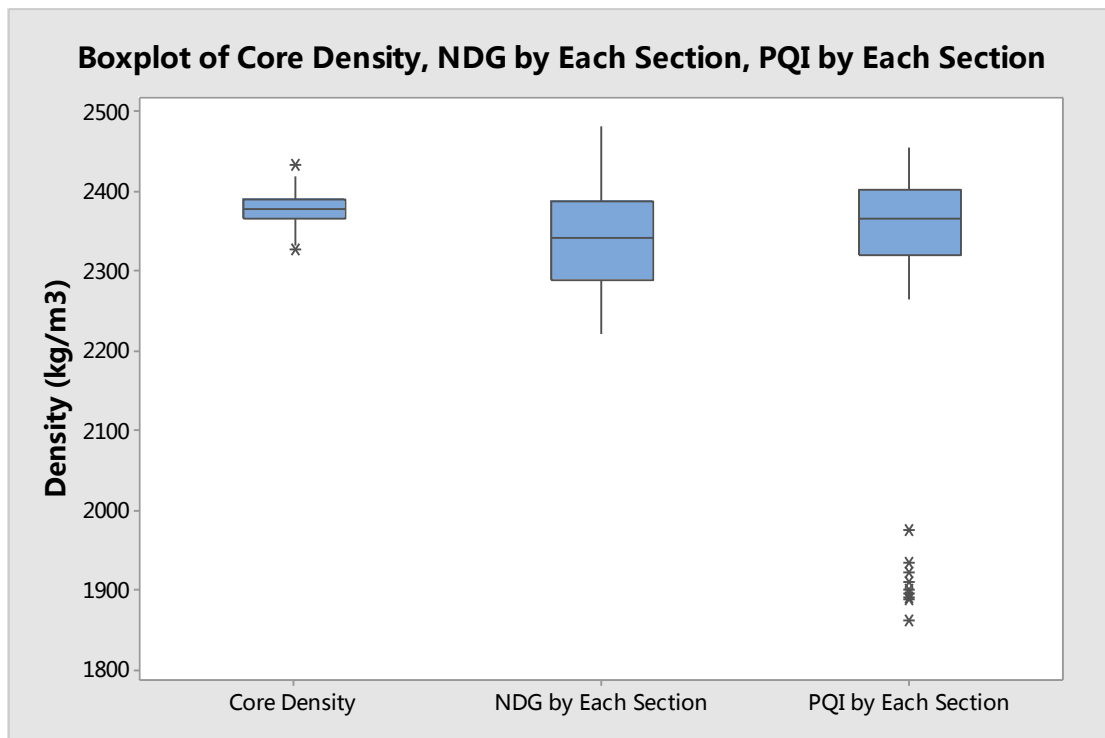


Figure 27 Boxplot of Calibrated Data by the Calibration Point in Each Section

5.5.3. HYPOTHESIS TESTING

A hypothesis test using a two sample T-test compares each data set with core density and checks if the mean density of each test method is different from the mean core density.

- The null hypothesis, H_0 , is that the means of the densities measured by PQI/NDG in wet/dry condition are equal to the mean of core densities.
- The alternative hypothesis, H_1 , is that the means of the densities measured by PQI/NDG in wet/dry condition are NOT equal to the mean of core densities.

The test statistic is $T = \frac{\bar{X}_1 - \bar{X}_2}{S_P \sqrt{\left(\frac{1}{n_1} + \frac{1}{n_2}\right)}}$, where S_P^2 is the pooled estimator of the common variance. The null distribution of T is $t(n_1 + n_2 - 2)$. Table 8 below provides a rough guide to interpreting the significance probabilities obtained from this distribution.

Table 8: Significance Probability and Interpretation

Significance Probability p	Rough Interpretation
$p > 0.10$	Little evidence against H_0
$0.10 \geq p > 0.05$	Weak evidence against H_0
$0.05 \geq p > 0.01$	Moderate evidence against H_0
$p \leq 0.01$	Strong evidence against H_0

The study in Table 9 uses the raw data and predicts the means of the following dataset are not equal to the mean core density – PQI Dry and Wet and NDG Wet. The only exception is that there is little evidence to show any difference between the mean of NDG Dry and the mean of core densities. In other words, the mean of NDG Dry is predicted equal to the mean core density. This reinforces what can be seen in the boxplot in Figure 23.

Table 9: Student's Two Sample T-Test Using Raw Data (Unit: kg/m³)

	Core Bulk Density	PQI		NDG	
		Dry	Wet	Dry	Wet
Mean	2378	2181	2307	2384	2464
N	60	60	60	60	60
s, Standard Deviation	22	68	103	48	77
s ² , sample variance	474	4683	10574	2293	5883
Sp ² , Pooled estimate of the common variance		2579	5524	1384	3179
T, Test Statistic		-21.22	-5.23	0.98	8.40
T (118) Quantile		>0.999	>0.999	<0.9	>0.999
p, significance probability		<0.001	<0.001	>0.1	<0.001
Rough Interpretation		Strong Evidence against H0	Strong Evidence against H0	Little Evidence against H0	Strong Evidence against H0

The study on the calibrated data, as summarized in Table 10, suggests the means of the calibrated NDG Dry and PQI Wet are different from the mean core density, but the means of the calibrated PQI Dry and NDG Wet densities may be considered equal. Figure 28 **Error! Reference source not found.** is the boxplot of the calibrated data.

The calibration process brought the means of PQI Dry and NDG Wet closer to the mean core density, but also reversed the trend for NDG Dry. This suggests the results are highly sensitive to the calibration. Although calibration using core densities is suggested in BS 594987 for all indirect density gauges, the mean of NDG Dry was closer to the mean core density before this calibration. This may provoke the question of whether NDG should follow the same calibration process. The pre-calibration using a standard block made of aluminium or magnesium might be a sound calibration method on its own. Further investigation is required to provide a definitive answer. For the purpose of this study, the same calibration process was followed for reasonable comparison.

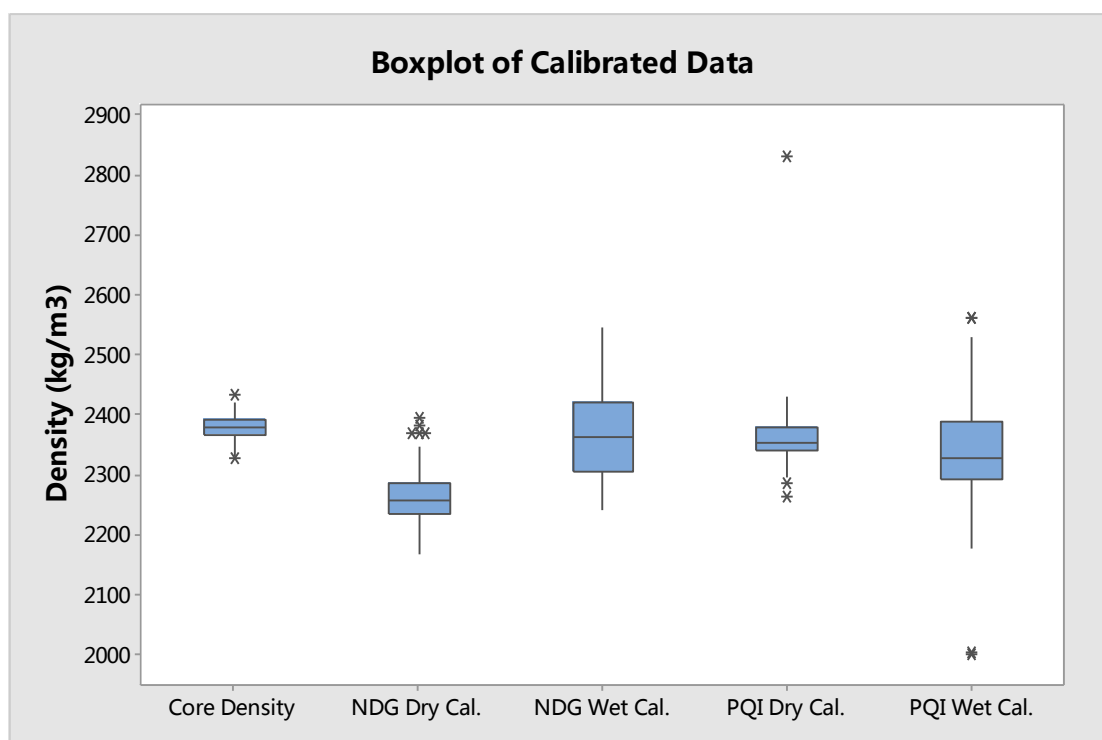


Figure 28 Boxplot of Calibrated Data

Table 10: Student's Two Sample T-Test Calibrated Data (Unit: kg/m³)

	Core Bulk Density	PQI		NDG	
		Dry	Wet	Dry	Wet
Mean	2378	2366	2333	2267	2370
N	60	60	60	60	60
s, Standard Deviation	22	68	103	48	77
s ² , sample variance	474	4683	10574	2293	5883
Sp ² , Pooled estimate of the common variance		2579	5524	1384	3179
T, Test Statistic		-1.27	-3.31	-16.25	-0.74
T (118) Quantile		<0.9	>0.999	>0.999	<0.9
p, significance probability		>0.1	<0.001	<0.001	>0.1
Rough Interpretation		Little Evidence against H0	Strong Evidence against H0	Strong Evidence against H0	Little Evidence against H0

6. ANALYSIS

6.1. REGRESSION ANALYSIS

Regression analysis generates an equation that describes the relationship between the predictor variables (also called “independent variables”, such as thickness, moisture, temperature etc) and the response variable (also called “dependent variable”, such as the PQI/NDG readings in this case). Furthermore, it examines whether any factors and their interactions have statistically significant effect on the results of the PQI/NDG readings and how influential they are. Air voids were calculated based on the maximum density of the mix and the core densities. Hence, they are correlated to core densities and not included in the following analysis as an independent variable.

6.2. PQI DENSITY REGRESSION ANALYSIS

In the multiple regression linear model of PQI density versus thickness, core density, H2O index, temperature and dry/wet condition (as a categorical variable, 0 = dry, 1 = wet), the factors and interactions in Table 11 are statistically significant based on p values < 0.05. Judging by the F-values, moisture represented by the factors of H2O index and Dry/Wet condition and their corresponding interactions played an important role in determining the PQI readings.

The stepwise regression automatically identifies a useful set of predictors and systematically adds the most significant variable or removes the least significant variable during each step. The adjusted percentage of variance accounted for is reasonable, at 59.92%.

The diagnostic plot in Figure 29 examines the model fit. The histogram shows the data can be considered normally distributed but some outliers are evident. The normal distribution of the residuals may be distorted by the outliers and this can be seen in the normal probability plot although overall this is considered acceptable. A randomly distributed residual versus fits plot verifies the assumption that the residuals have a constant variance, although an occasional high residual are evident in the plot. The fitted value plot verifies the assumption that the residuals are uncorrelated with each other. Overall, a multiple regression model in Table 11 appears to be tenable.

Table 11: Analysis of Variance for PQI Density

SOURCE	DF ⁴	ADJ SS ⁵	ADJ MS ⁶	F-VALUE ⁷	P-VALUE ⁸
Thickness	1	51627	51627	16.43	0.000
Core Density	1	41718	41718	13.27	0.000
H2O	1	95756	95756	30.47	0.000
Temperature	1	55637	55637	17.70	0.000
Dry/Wet	1	24742	24742	7.87	0.006
Thickness x Temperature	1	49802	49802	15.85	0.000
Core Density x H2O	1	83062	83062	26.43	0.000
H2O x Dry/Wet	1	195319	195319	62.15	0.000
Dry/Wet x Temperature	1	25434	25434	8.09	0.005
Thickness x Dry/Wet	1	18850	18850	6.00	0.016
Error	109	342580	3143		
Total	119	933223			

Regression Equation (Dry-0/Wet-1):

- 0 PQI Density = 1138 + 1.870 Core Density + 335.8 H2O – 152.6 Temperature – 87.7 Thickness – 0.1227 Core Density x H2O + 3.619 Temperature x Thickness
- 1 PQI Density = 2403 + 1.870 Core Density + 291.1 H2O – 205.9 Temperature – 80.0 Thickness – 0.1227 Core Density x H2O + 3.619 Temperature x Thickness

⁴ DF denotes degree of freedom.

⁵ ADJ SS denotes adjusted sum of squares. “Sum of squares represents a measure of variation or deviation from the mean.” (Minitab 17 Help)

⁶ ADJ MM denotes adjusted mean squares, = sum of squares / degree of freedom. (Minitab 17 Help)

⁷ F-VALUE “calculated by dividing the factor MS by the error MS.” A large F-ratio indicates the variation among groups is more than expected. (Minitab 17 Help)

⁸ P-VALUE “used to determine whether a factor is significant; typically compare against an alpha value of 0.05. If the p-value is lower than 0.05, then the factor is significant.” (Minitab 17 Help)

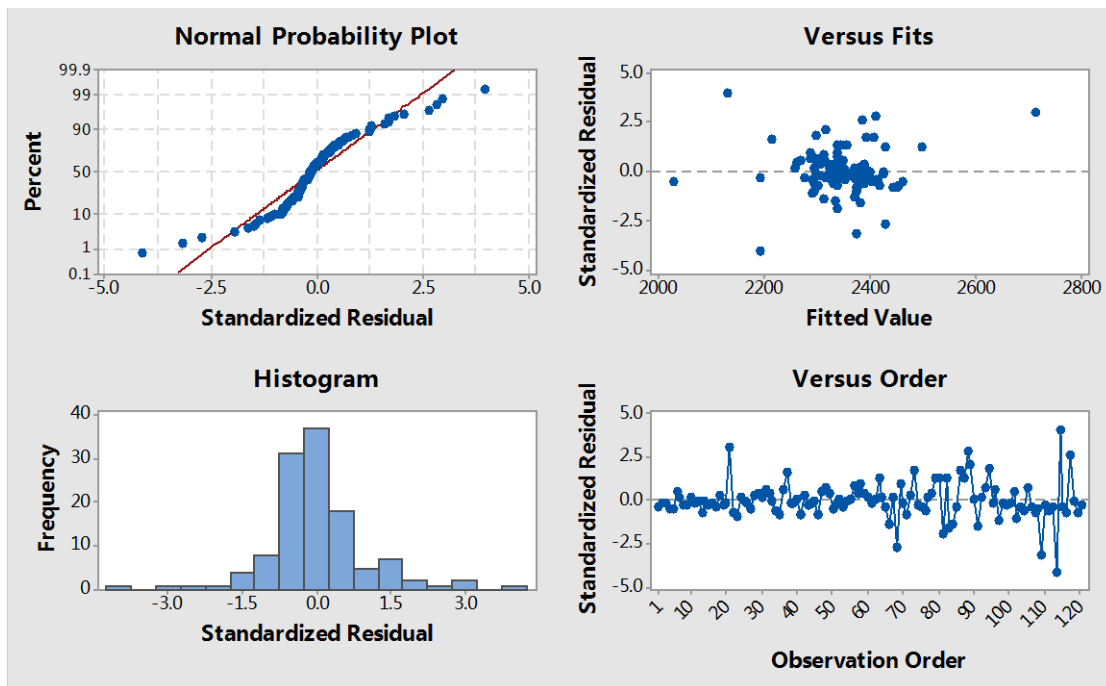


Figure 29 Diagnostic Plots for PQI Density

6.3. NDG DENSITY REGRESSION ANALYSIS

In the multiple regression model of NDG density versus thickness, core density, air void and dry/wet condition, only the factors of core density and dry/wet are statistically significant based on p values < 0.05. The stepwise regression automatically identifies a useful set of predictors and systematically adds the most significant variable or removes the least significant variable during each step. The adjusted percentage of variance accounted for is 41.19%. The thickness did not appear to be an influential factor in the model. The NDG density also appears to be affected by the dry/wet condition, which reinforced the finding in Figure 23.

The diagnostic plots in Figure 30 examine the model fit. The histogram shows the data are slightly left-skewed but the assumption of normality is considered tenable. The normal probability plot is distorted at the ends but is considered acceptable. The fitted value plot appears random but in two clusters which might correspond with wet and dry readings. The versus-order plot shows a number of high residuals.

A randomly distributed residual versus fits plot verifies the assumption that the residuals have a constant variance. Residual versus observation data verifies the assumption that the residuals are uncorrelated with each other.

Table 12: Analysis of Variance for NDG Density⁹

SOURCE	DF	ADJ SS	ADJ MS	F-VALUE	P-VALUE
Core Density	1	20261	20261	5.13	0.025
Dry/Wet	1	316932	316932	80.23	0.000
Error	117	462160	3950		
Total	119	555781			

Regression Equation (Dry-0/Wet-1)

0 NDG Density = 836 + 0.602 Core Density

1 NDG Density = 939 + 0.602 Core Density

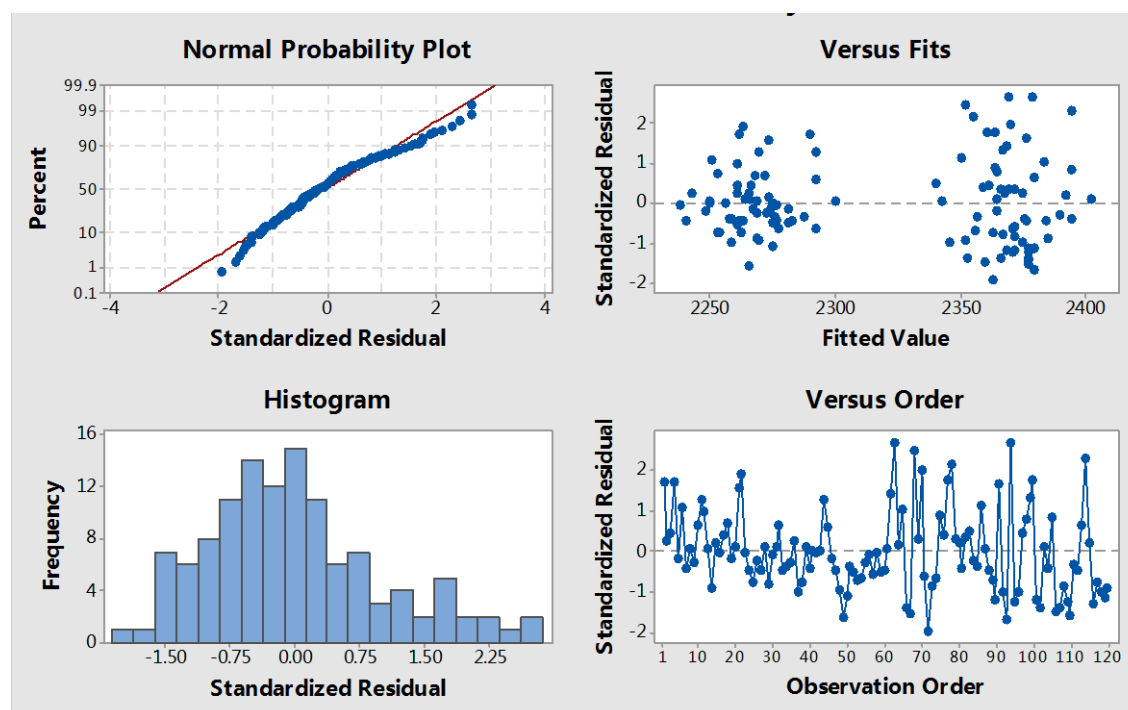


Figure 30 Diagnostic Plots for NDG Density

⁹ See abbreviations in Table 11.

6.4. MEASUREMENT ERRORS

The above regression analyses suggest that moisture plays an important role in the precision of PQI measurements. It is therefore useful to further explore how the H2O index relates to the difference between PQI and core density. Error in PQI measurements is defined as the percentage of the difference between PQI and core density divided by the core density as shown below. Its relationship with the H2O index is plotted in Figure 31. The findings are summarized as follows.

$$\text{Error in PQI Density (\%)} = \frac{\text{PQI Density} - \text{Corresponding Core Density}}{\text{Corresponding Core Density}} \times 100\%$$

- When $H_2O \leq 12$, 100% of the measured densities are within $\pm 5\%$ of the core densities.
- When $12 < H_2O \leq 25$, 79% of the measured densities are within $\pm 5\%$ of the core densities.
- When $H_2O > 25$, 56% of the measured densities are within $\pm 5\%$ of the core densities.

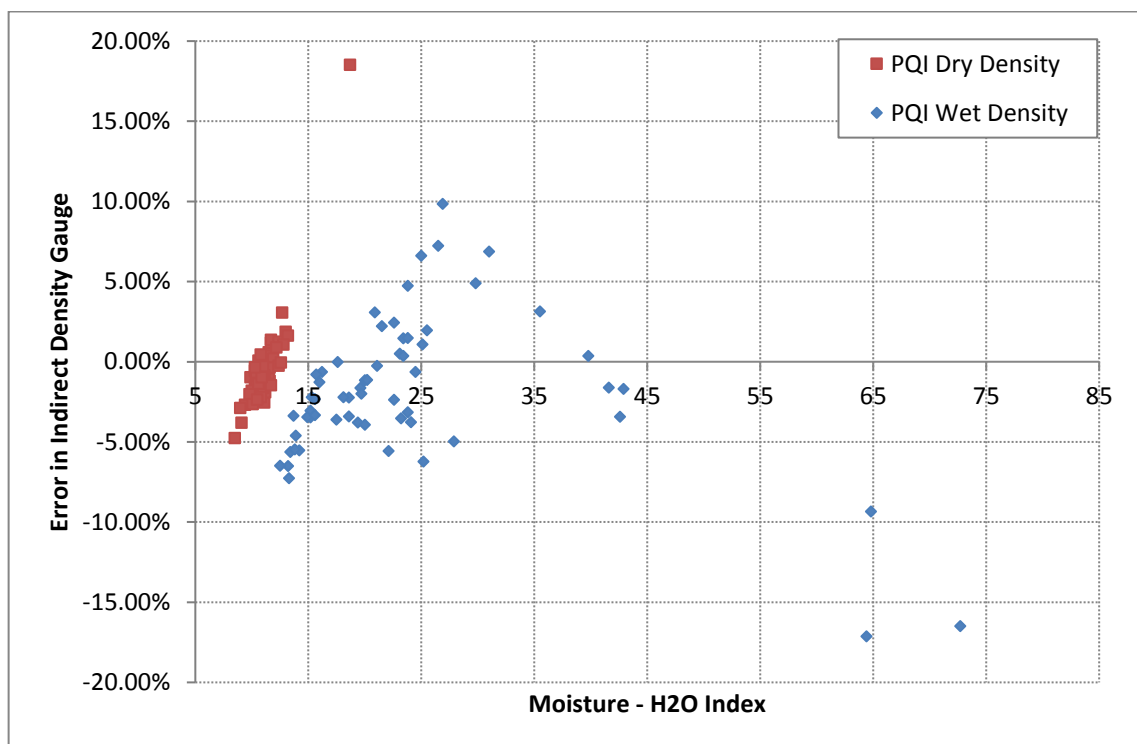


Figure 31 Error in Measured Density

An ideal density measurement system used to check compaction compliance should provide “Indirect Density Gauge Measured Air Voids = Core Sample Bulk Density Air Voids”, as the red line in Figure 32. It may be acceptable to set a small tolerance for higher air voids, to be conservative. But any measured air void less than the lab air void would be a “false reading”, since this may

dismiss non-conforming areas of insufficient compaction. Hence, any points below the red line could be considered false readings. This is summarized in Table 13 based on a total of 60 readings in each category. As shown in Figure 32, data taken in the wet appears to be more affected.

Table 13: Summary of False Readings

	NDG DRY	NDG WET	PQI DRY	PQI WET
No. of False Readings	1	26	15	17
% of False Readings	2%	43%	25%	28%

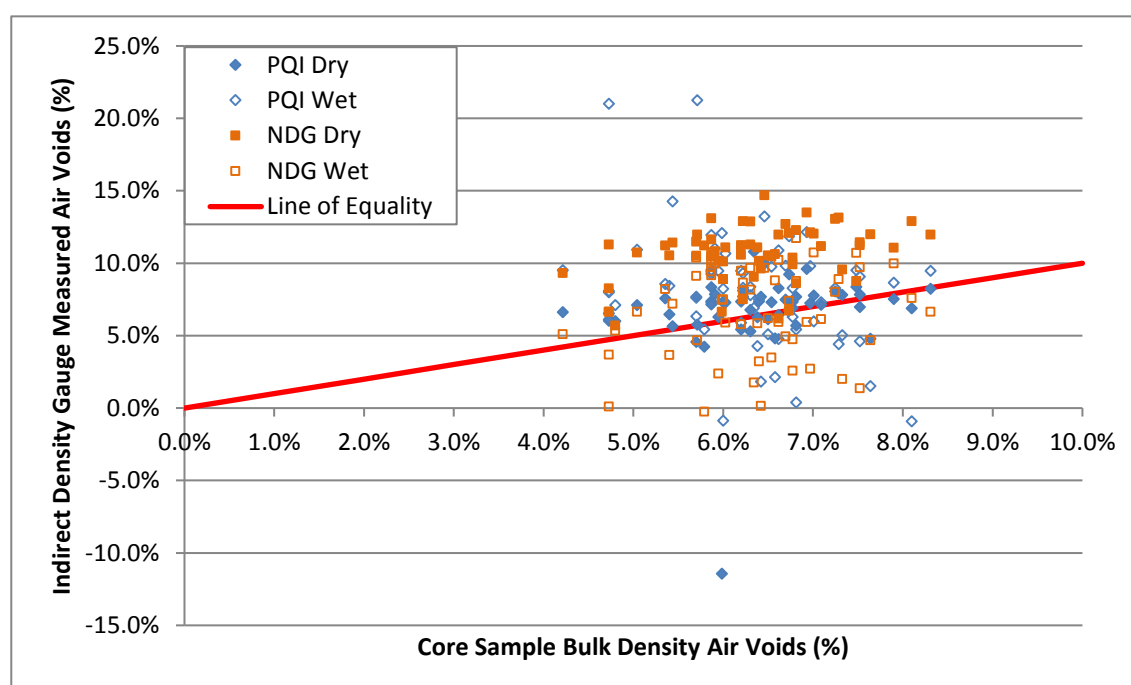


Figure 32 Air Voids

6.5. GAGE R&R STUDY – NESTED ANOVA

Gage repeatability and reproducibility study (Gage R&R Study) assesses the ability of the PQI measurement to determine if it can detect any meaningful differences in process variables. According to Minitab 17 Support, repeatability is defined as “the ability of an operator to consistently repeat the same measurement of the same part, using the same gauge under the same condition” and reproducibility is defined as “the ability of a gauge, used by multiple operators, to consistently reproduce the same measurement of the same part, under the same conditions”. The terminologies in the study are based on production environments, where it may be used to assess the factory measurement systems in discriminating between different parts and/or the

variability caused by different operators. In our case, “part” means testing location. “Part-To-Part” represents from the density variation from one testing location to another.

Three repeated readings were taken at 54 testing locations (excluding the calibration points in each section). Although only two operators were involved in the test, each section was assumed to have a different operator to balance the study. The assessment of the reproducibility is not valid and was discarded, but the repeatability was considered valid. The “Total Gage R&R” is considered as the performance of the overall measurement system with primary contribution from repeatability. The NDG measurements were taken by others and only the averaged reading at each location was provided. Hence, the NDG measurements cannot be assessed for the R&R.

There are two main types of gage R&R – crossed and nested. In this case, the nested study is applicable.

- Gage R&R Study (Crossed): The same samples are repeatedly measured by independent operators,
- Gage R&R Study (Nested): The samples are measured by one assigned operator only.

Figure 33 and Table 15 summarize the analysis results. Looking at the %Contribution columns for Total Gage R&R and Part-to-Part, it can be seen that the percent contribution for differences between parts (Part-To-Part = 96.43) is much larger than the percentage contribution for measurement system variation (Total Gage R&R = 3.57). The %Study Var column indicates that the Total Gage R&R equals 18.90% of the study variation and the Part-To-Part equals 98.20% of the study variation. Hence, most of the variation is due to differences between testing locations and little is due to measurement system errors.

An important index is the number of different categories, which estimates how many separate groups of samples the system can distinguish. This number represents the number of non-overlapping confidence intervals that will span the range of product variation. The result of 7 in Table 15 indicates the system can distinguish between parts very well.

The R chart displays the operator consistency. The points above the upper control limit indicate the operator is not consistently measuring the parts. The UCL takes into account the number of times each operator measures a part. If operators measure consistently, the ranges are small relative to the data and the points fall within the control limits. This chart is helpful in identifying any inconsistent operator and identifying specific parts that were not homogeneous. In this case, the section 1 was measured by operator 1 and the rest of the sections were measured by operator 2. It appears the measurements by the two operators are consistent, despite of three samples in sections 4 and 6 being potential outliers.

The Xbar chart compares the part-to-part variation to the repeatability component. The plotted points are the average measurement of each part. The centre line is the overall average for all part measurements by all operators. The control limits are based on the number of measurements in each average and the repeatability estimate. A high proportion of the points are outside the control limits, indicating that the measurement system is capable of detecting between-part differences over the repeatability error.

The following guidance in Table 14 was provided in Automobile Industry Action Group (AIAG) for assessing the measurement system. The PQI measurement falls in the middle range by both the percentage of study variation and the percentage of contribution. In other words, the system is acceptable in detecting the sample difference for quality control.

Table 14: Guidance for Measurement System Assessment

TOTAL GAGE R&R PERCENTAGE IN		INTERPRETATION
%STUDY VAR	%CONTRIBUTION	
Less than 10%	Less than 1%	The measurement system is acceptable
Between 10% and 30%	Between 1% and 9%	The measurement system is acceptable depending on the application, the cost of the measuring device, cost of repair, or other factors.
Greater than 30%	Greater than 9%	The measurement system is unacceptable and should be improved.

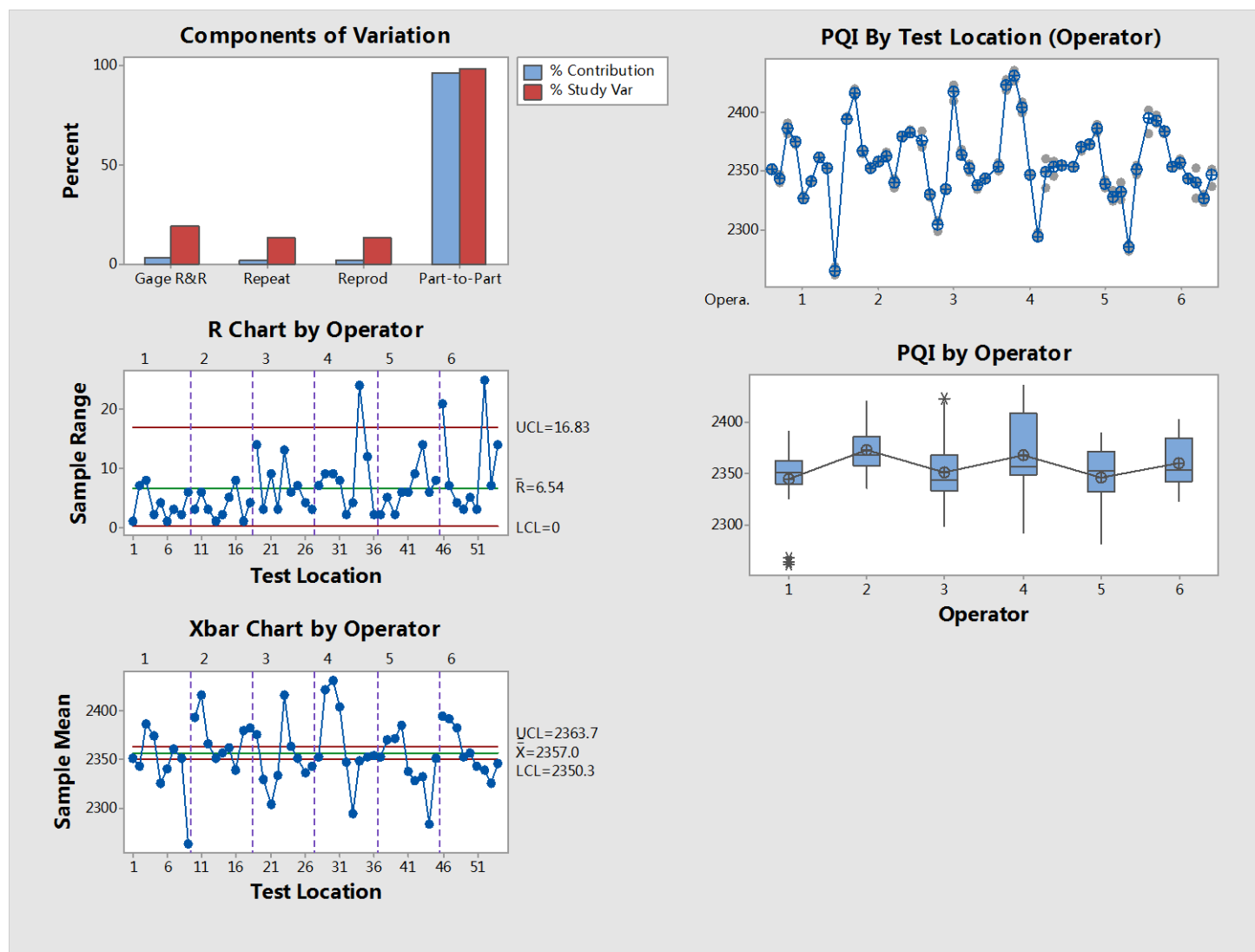


Figure 33 Gage R&R (Nested) Report

Table 15: Results of Gage R&R (Nested) for PQI Measurement

Number of Distinct Categories = 7

Source	DF	SS	MS	F	P
Operator	5	18008	3601.61	1.162	0.341
Location (Operator)	48	148761	3099.18	159.437	0.000
Repeatability	108	2099	19.44		
Total	161	168868			

Source	Var Comp	% Contribution (of Var Comp)
Total Gage R&R	38.05	3.57
Repeatability	19.44	1.83
Reproducibility	18.61	1.75
Part-To-Part	1026.58	96.43
Total Variation	1064.63	100.00

Source	Std Dev (SD)	Study Var (6 x SD)	% Study Var (%SV)
Total Gage R&R	6.1682	37.009	18.90
Repeatability	4.4089	26.453	13.51
Reproducibility	4.3138	25.883	13.22
Part-To-Part	32.0403	192.242	98.20
Total Variation	32.6286	195.772	100.00

7. CONCLUSIONS AND RECOMMENDATIONS

7.1. CONCLUSIONS

The objective of the research was to review and evaluate the available methods of measuring the density of hot mix asphalt (HMA) pavements, specifically thin layers.

A comparison was undertaken between conventional coring bulk density methods (Destructive) with methods such as Nuclear Density Gauge (NDG), electromagnetic, GPR, Step frequency radar and indirect (non-destructive) compaction monitoring systems. Advantages and dis-advantages were addressed based on literature reviewed. It was determined that trialling more mature methods would provide a more industry ready/usable conclusion, particularly as there was difficulty sourcing certain models and equipment within the UK.

For laboratory testing the Nuclear Density Gauge and Pavement Quality Indicator were compared with each other and against the conventional coring method. The trials were designed to identify accuracy whilst determining moisture and thickness susceptibility. A local contractor constructed the asphalt trial at AECOM Nottingham Test Pit Facility (TPF), with various lift thicknesses and degrees of compaction.

The precisions of both PQI and NDG readings are highly sensitive to the on-site calibration. Detailed guidance on the calibration process is required for the use of NDG and PQI. It is recommended to take regular calibration and to calibrate using a good spread of core densities, e.g. 4% as suggested in BS 594987. Although BS 594987 recommends calibration using core densities for all indirect density gauges, the mean of NDG Dry was closer to the mean core density without this calibration. This may suggest the NDG pre-calibration using standard blocks is a sound calibration method on its own. However, this is to be justified in further investigations.

The core density is the only direct measurement of the density and is used as the calibration reference. Hence it is not included in the comparison.

A linear regression model was applied to examine the influential factors in the PQI and NDG measurement systems. Thickness appears to be a statistically significant factor for PQI but not for NDG. Although the manufacturer claims the moisture and temperature have been taken into account in the built-in algorithm in PQI, moisture represented by H2O index and Dry/Wet condition was predicted to be an influential factor in determining the PQI readings, so was temperature. NDG also showed variable readings in the surface wet condition. Therefore, it is prudent to take density measurements when the surface is dry using either PQI or NDG.

Romero (2000) suggested the moisture condition of $H_2O < 5$ for reliable PQI readings. However it was difficult to achieve even on a dry surface. The minimum H2O index in the surface dry condition was 8.5. It is found that when $H_2O \leq 12$, all the measured densities are within $\pm 5\%$ of the

core densities. As the moisture level increased, the PQI measurements were more likely to deviate from the corresponding core densities.

Comparing the measured air voids and the laboratory air voids, it is noted only 2% of NDG Dry readings are less than the laboratory air voids, compared to 25% of PQI Dry. Testing under the surface wet condition tends to introduce higher number of false readings for both NDG and PQI.

PQI and NDG are considered inadequate for quality assurance testing due to the wide spread of data and sensitivity to calibration. But they are tenable for quality control testing. PQI is considered acceptable in detecting the sample difference for quality control.

7.2. RECCOMENDATIONS

Indirect density measurements are subject to calibration and moisture condition. Current equipment available to the market is not adequate for QA but acceptable for QC. To improve the precision of indirect density gauges there should be:

- A sound method for calibration.
- The ability to consider moisture effect, and record/report details.
- To be considered for QA acceptance, only if $\pm 5\%$ variation from core densities can be demonstrated.

Later versions of the NDG and PQI may have increased precision, however, they are not currently available in the UK for testing.

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